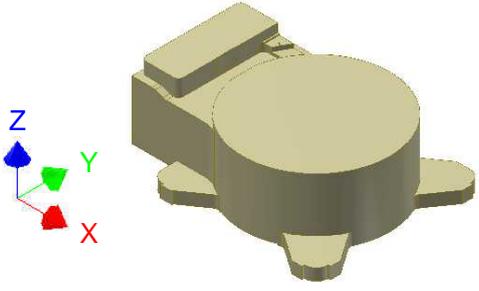
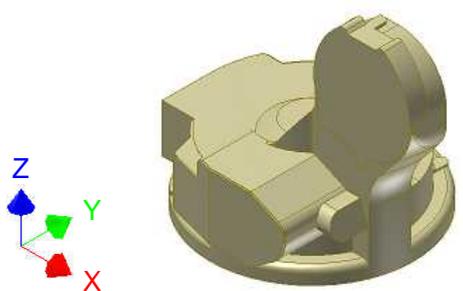
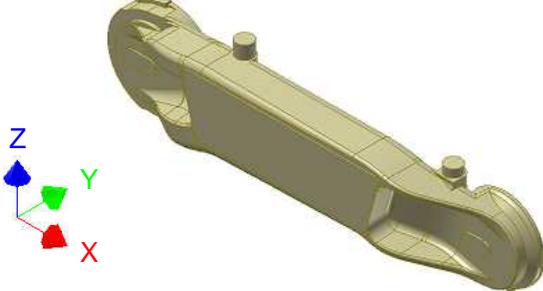
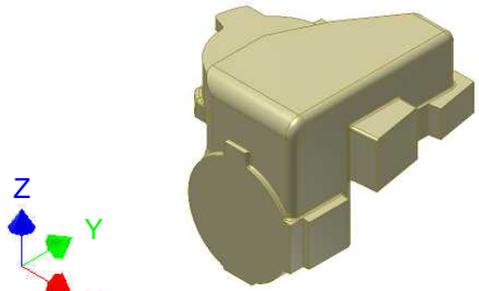
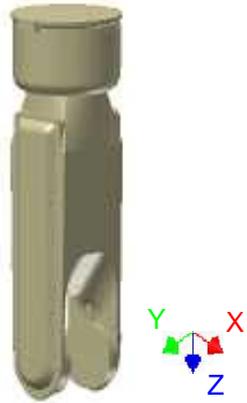
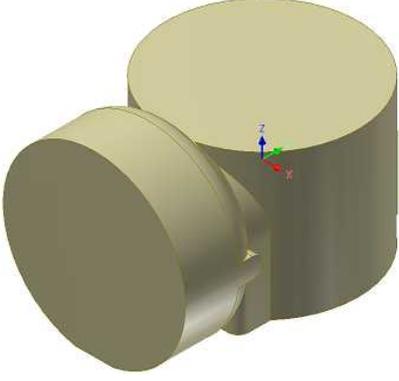
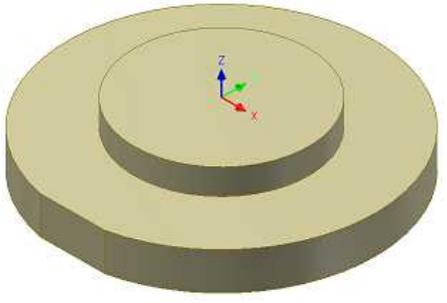


<p>Base</p>  <p>原点：ロボット取付中心</p>	<p>Link1</p>  <p>原点：ロボット取付中心</p>	
<p>Link2</p>  <p>原点：ロボットセンタと J2 回転中心の交わる点</p>	<p>Link3</p>  <p>原点：ロボットセンタと J3 回転中心の交わる点</p>	
<p>Link4</p>  <p>原点：J4 軸と J5 軸交わる点</p>	<p>Link5</p>  <p>原点：J4 軸と J5 軸交わる点</p>	<p>Link6</p>  <p>原点：ツール取付面と J6 軸の交点</p>

