

Synchro-feed Welding System

Next Generation Model of
Ultra Low Spatter Welding
System

NEW

Synchro-feed Evolution

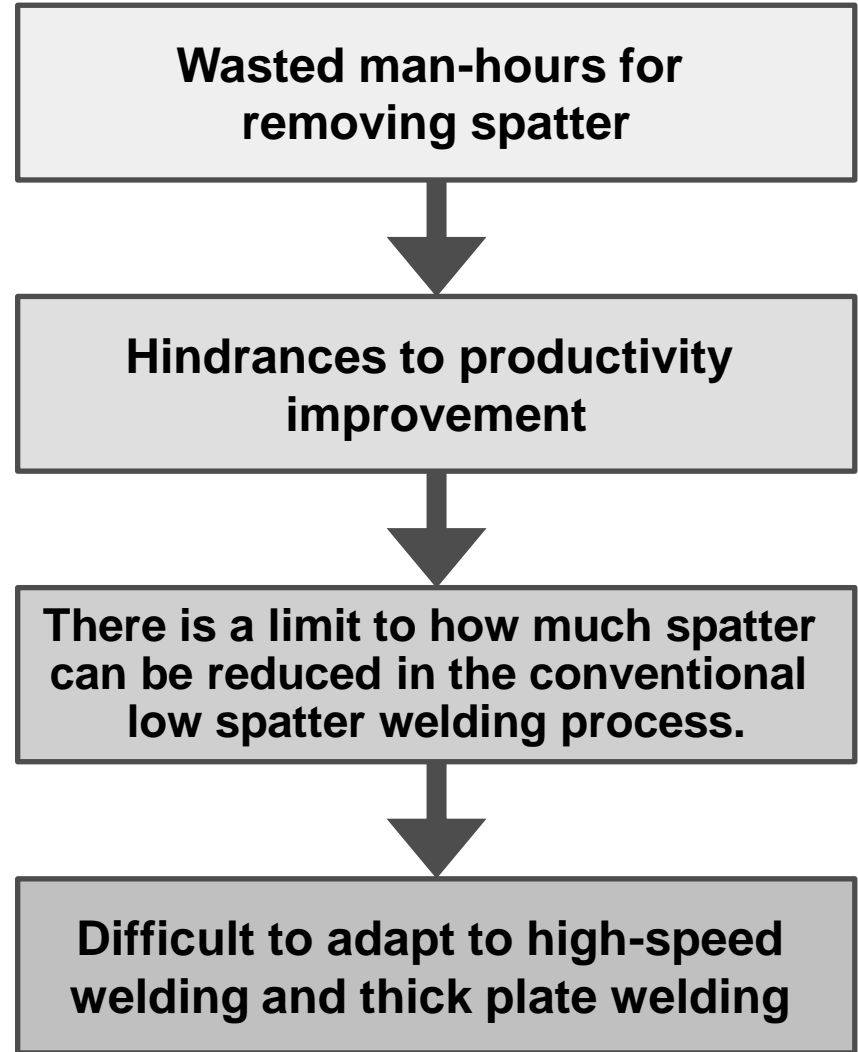


Almega Friendly series II

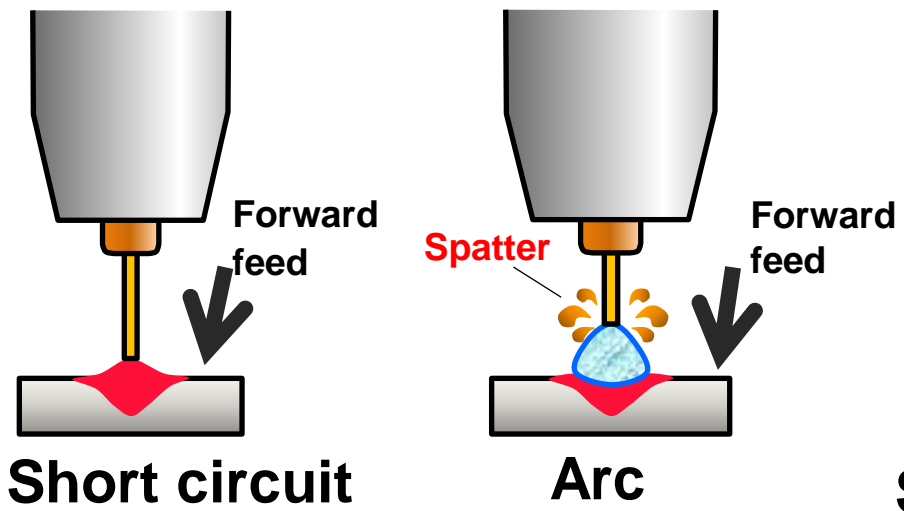
Synchro-feed has been made easier to use and more powerful.

1. Synchro-Feed Welding Process
2. New Control: Push-Arc Process
3. New Control: Synchro-Feed Pulse
4. Simple Connection and Easy Maintenance
5. Two Types of Synchro-Feed

Removing spatter Reducing man-hours

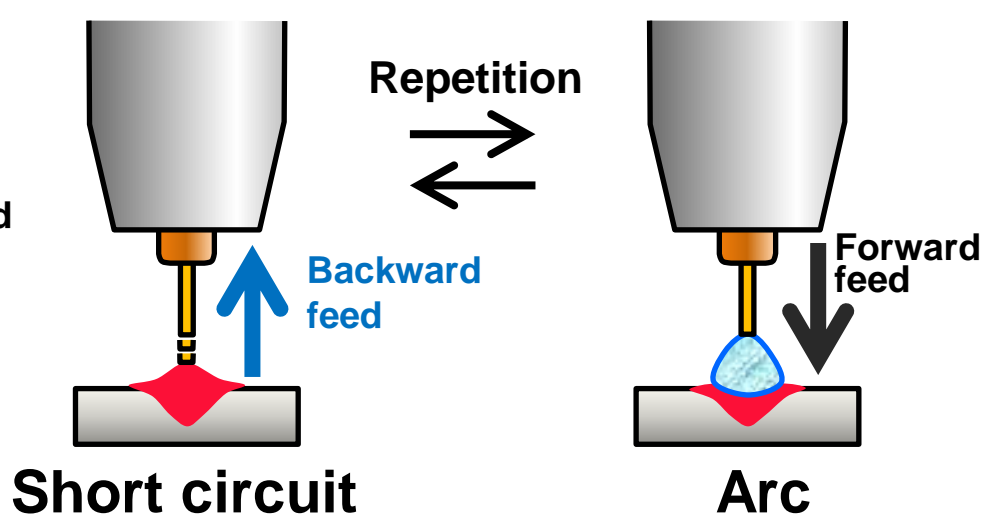


Conventional welding process



Wire is always fed forward

Synchro-feed welding process



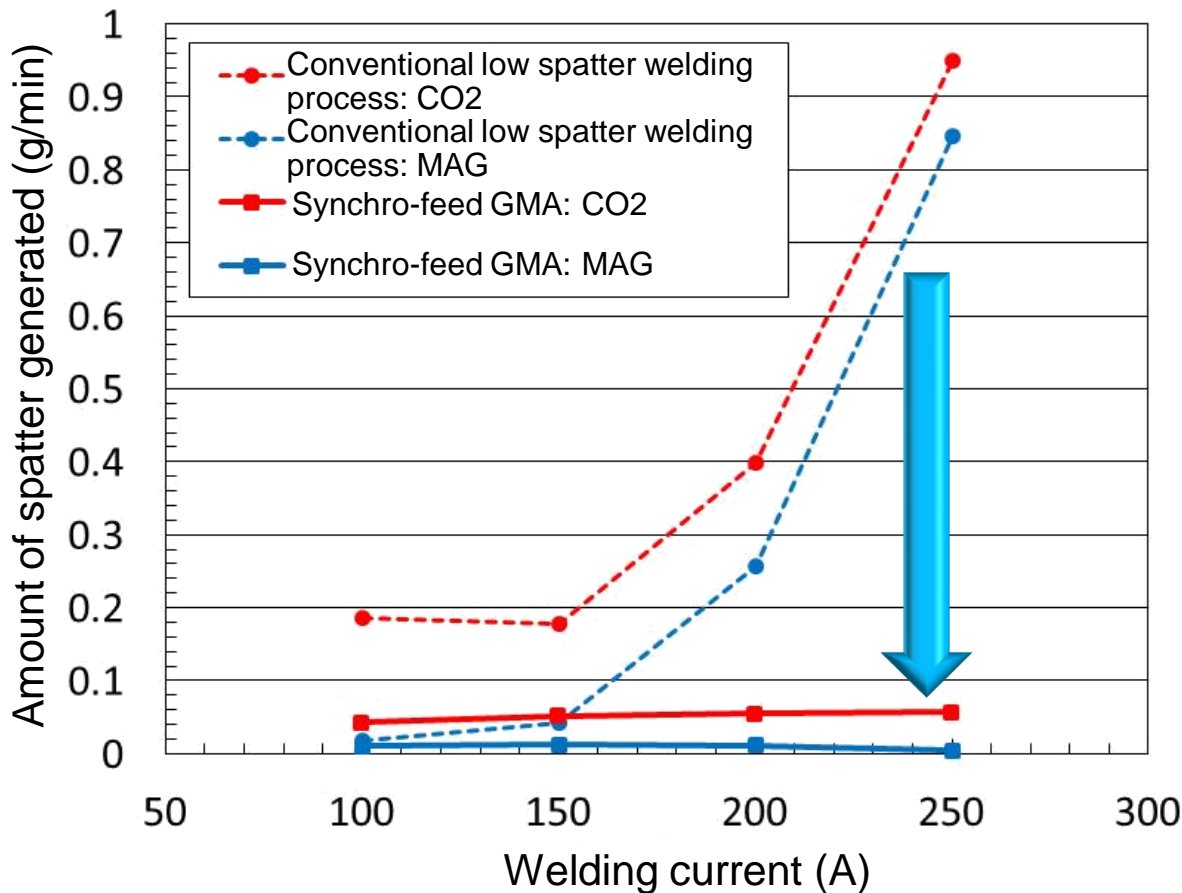
Repeated forward and backward feed of wires

+ In addition,

**Achievement
of high quality
welding**

Daihen's original current waveform control

Maximum 99 % spatter reduction



Spatter is significantly reduced in all current ranges!

Less than 1/10th of spatter was generated compared to the conventional welding process!

Synchro-feed significantly reduces spatter

Reduces the amount of spatter generated to 0.1 g/min or less in all areas

Comparison of the amount of spatter generated



Conventional welding process

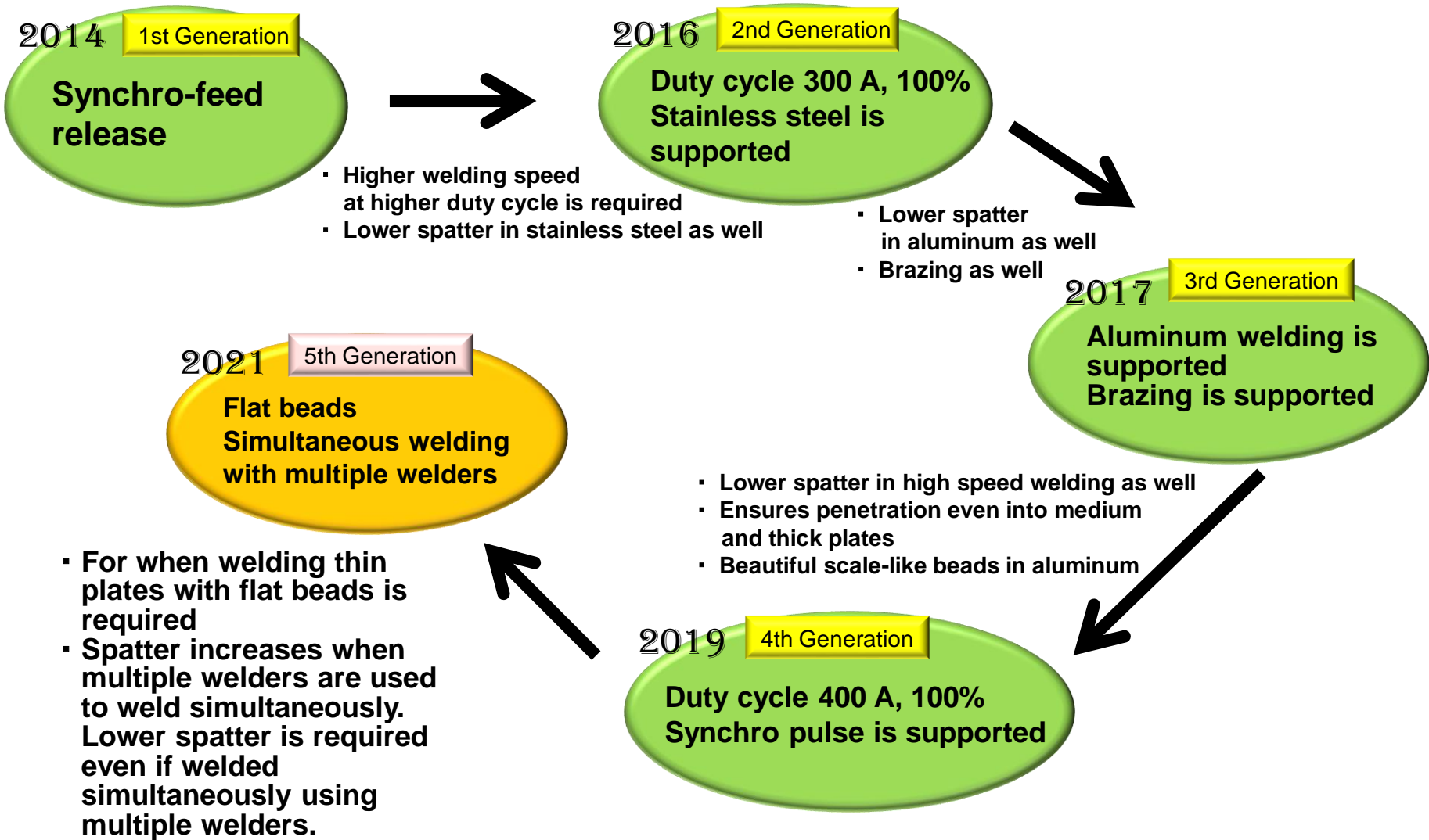


Synchro-feed

<Conditions>
Average wire feed rate: 12 m/min
Short circuit and arc cycle: 100 Hz
Average current: 280 A
Welding speed: 100 cm/min
Shielding gas: CO2

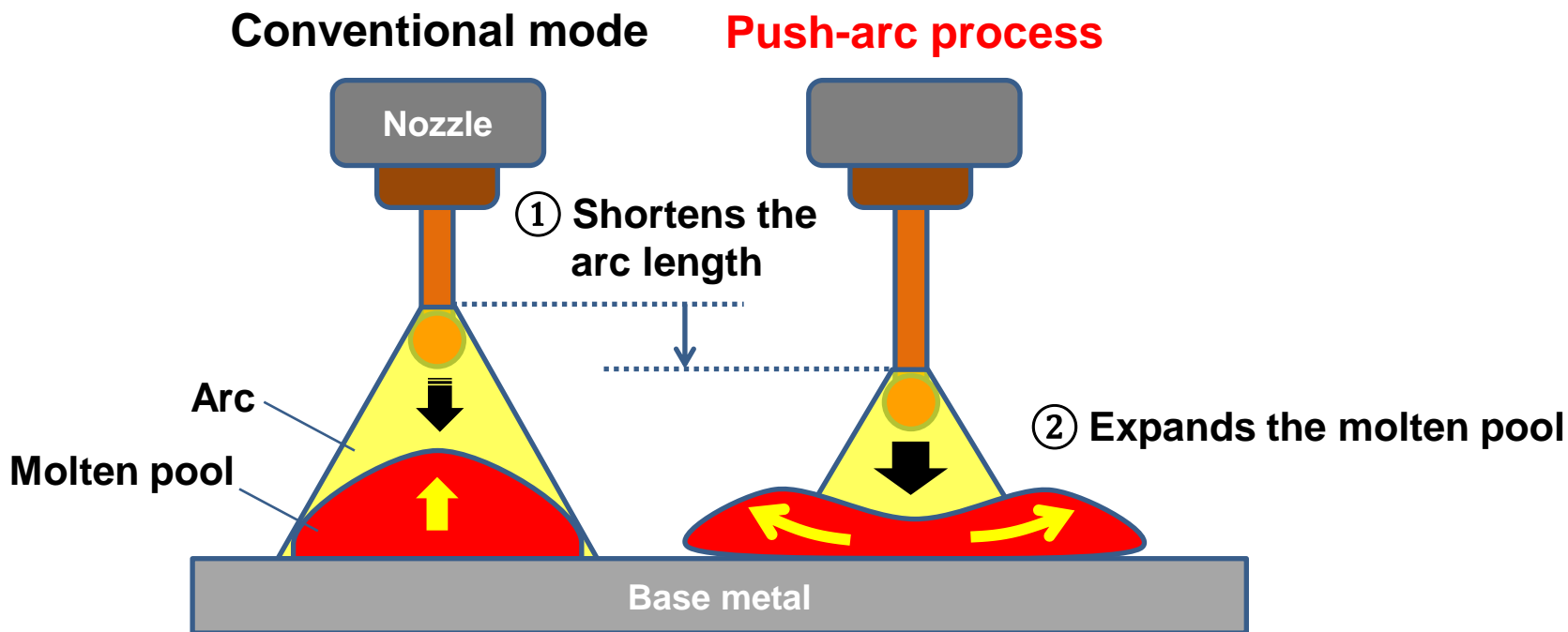
**Synchro-feed
Significantly
reduces spatter**

Developing the Push-Arc Process



What is push-arc process?

The Welding mode improves the wire feed frequency over conventional Synchro-feed welding and improves tolerance of joint resistance by placing **wide and flat beads** while **maintaining conventional low spatter performance** through application of new waveform control.

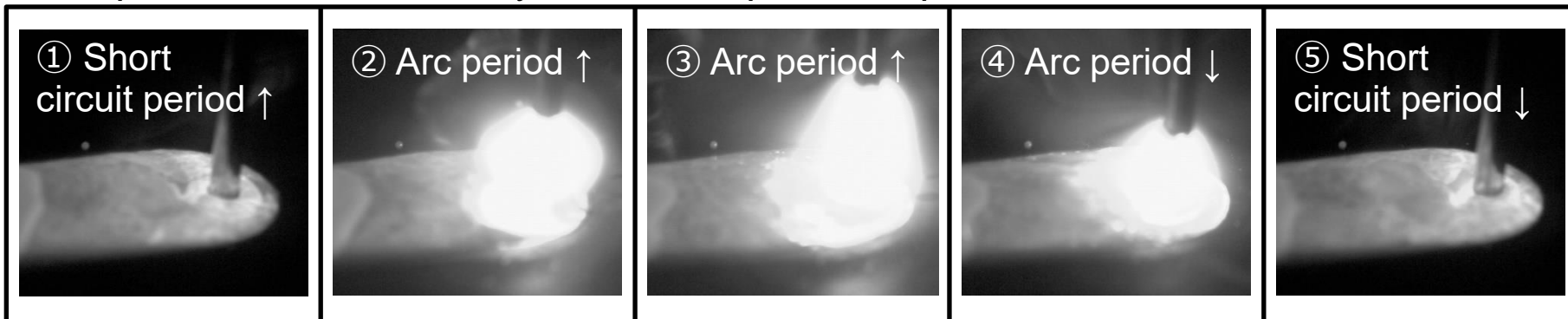


■ Points

“Wide weld beads are formed due to the ‘① short arc length’ and by ② expanding the molten pool”

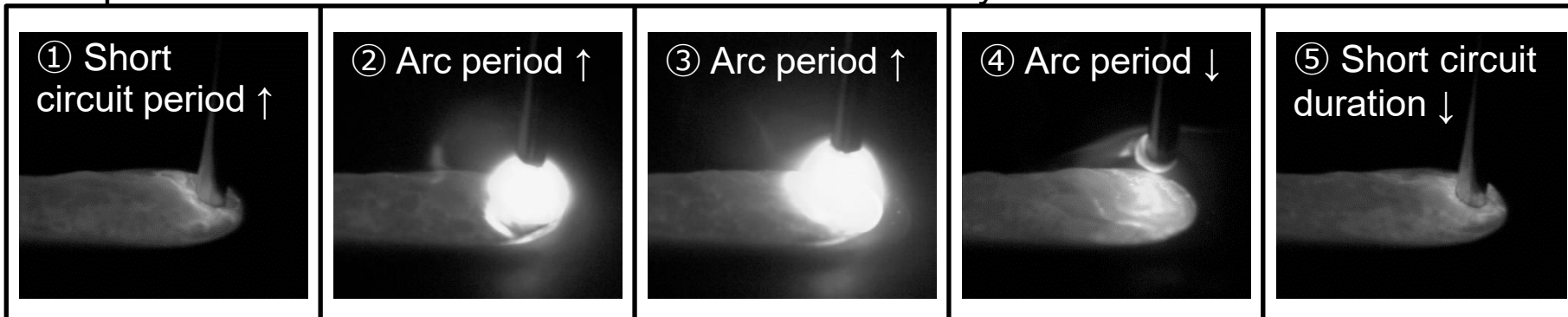
Principles of the Push-Arc Process

Droplet transfer in CO2 Synchro-feed push-arc process



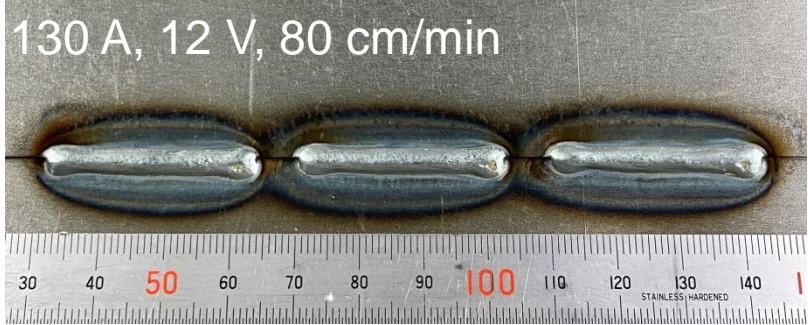
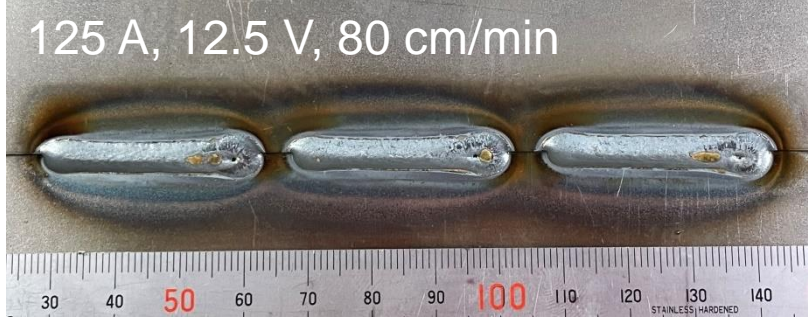
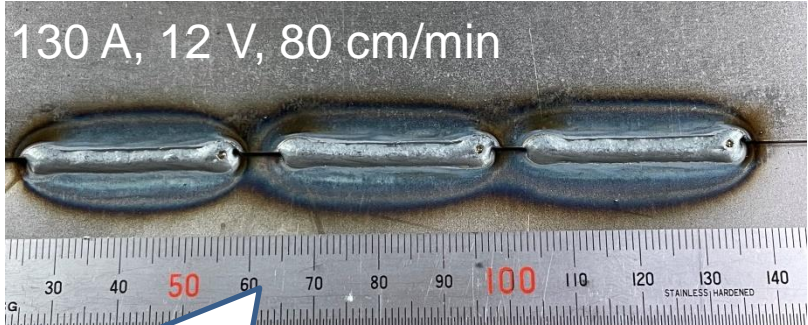
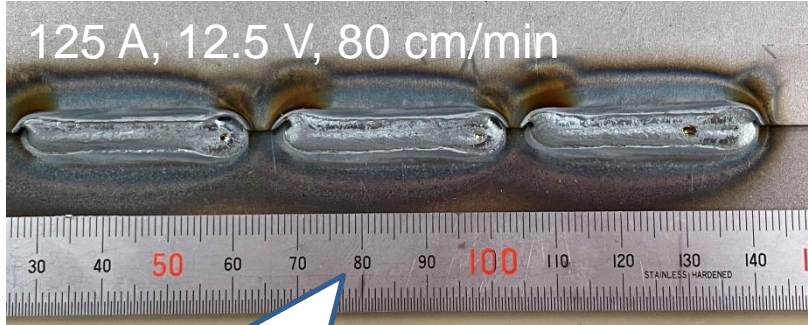
The above photos ① to ③ show backward feed of wire while ④ and ⑤ show forward feed of wire. ① The wire is fed backward from the state of short circuit. ② An arc is generated. The wire is fed backward with the arc output to the state of ③. ④ A switchover to the state of feeding wire forward causes beads to expand by continuing the arc period during this time. The wire is short-circuited in ⑤ and then back to ① to repeat the short circuit and arc.

Droplet transfer in the conventional mode of CO2 Synchro-feed



The above photos ① to ③ show the backward feed of wire while ④ and ⑤ show forward feed of wire. ① The wire is fed backward from the state of short circuit. ② An arc is generated. The wire is fed backward to the state of ③, ④ the current value is kept low when the wire is fed forward, and the wire is short-circuited as in ⑤, and then back to ① to repeat the short circuit and arc.

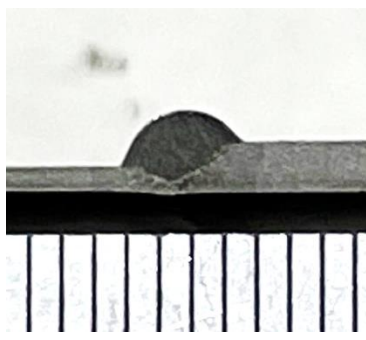
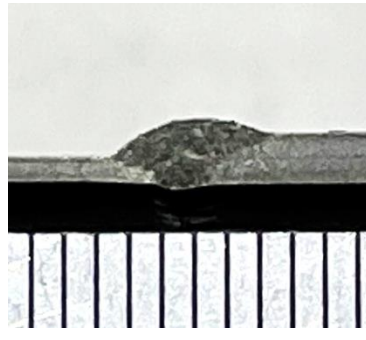
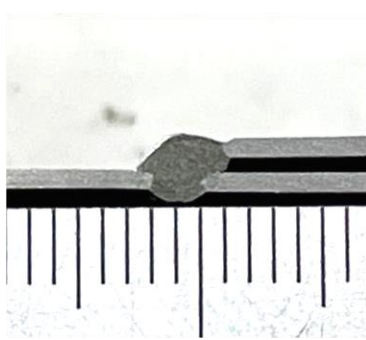
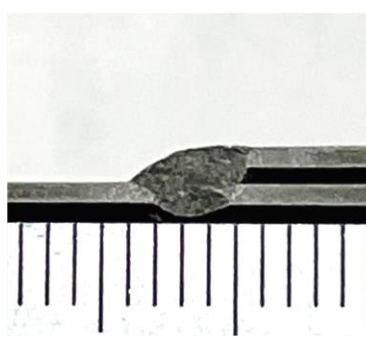
Lap joint welding of 0.8 mm thick plate (wire diameter $\phi 1.2$)

Gap	Conventional Synchro-feed	Push-arc process
0 mm	<p>130 A, 12 V, 80 cm/min</p> 	<p>125 A, 12.5 V, 80 cm/min</p> 
0.8 mm	<p>130 A, 12 V, 80 cm/min</p> 	<p>125 A, 12.5 V, 80 cm/min</p> 

Thin bead and undercutting tends to occur

Wide beads have been achieved

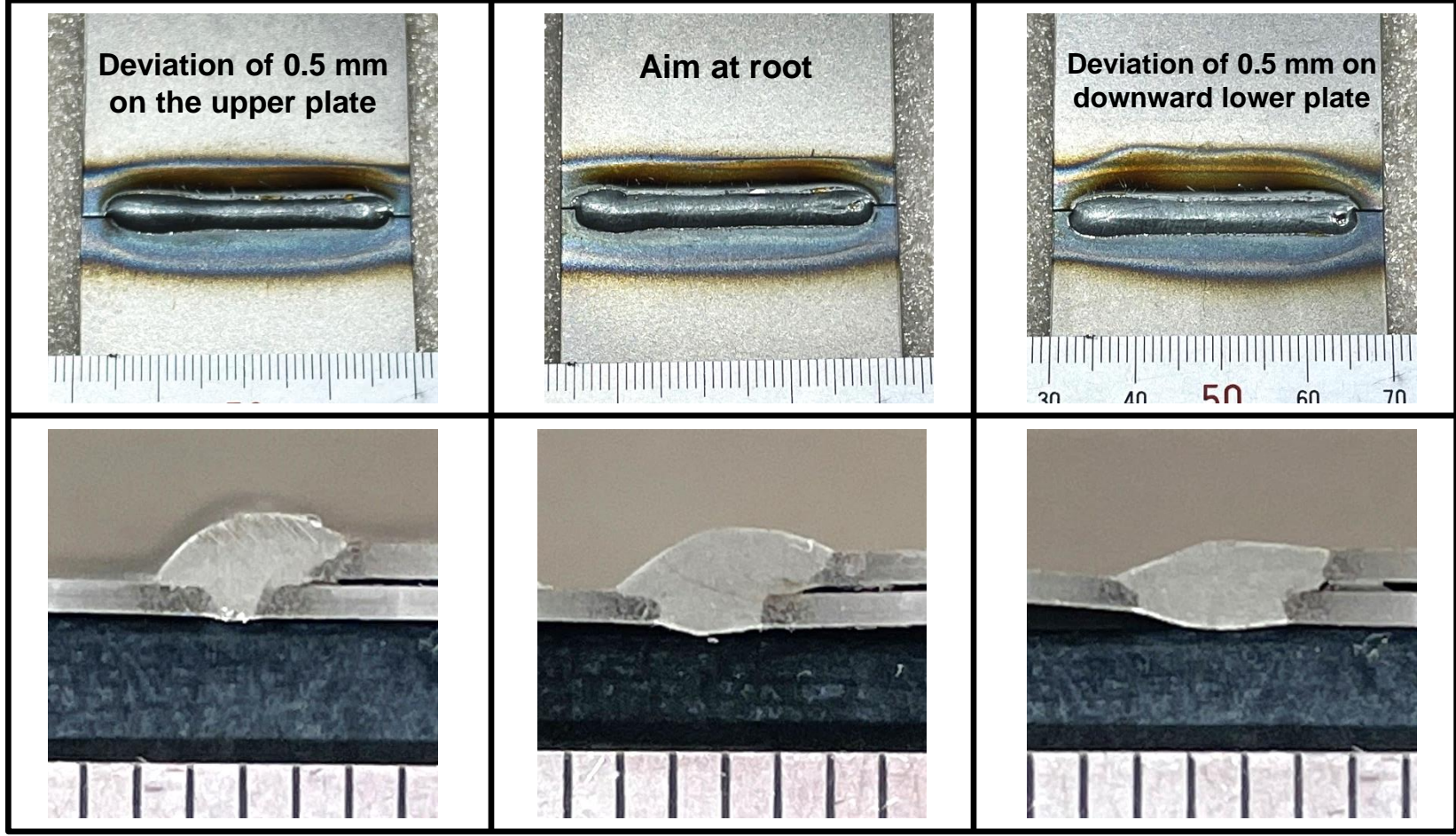
Lap joint welding of 0.8 mm thick plate (wire diameter $\phi 1.2$)

Gap	Conventional Synchro-feed	Push-arc process
0 mm	 <p data-bbox="676 578 985 628">Emboss bead</p>	 <p data-bbox="1516 549 1816 649">Flat and wide bead</p>
0.8 mm	 <p data-bbox="676 892 994 1056">Thin bead and undercutting tends to occur.</p>	 <p data-bbox="1516 921 1825 1028">Flat and wide bead</p>

Welding Sample (Mild Steel, MAG Welding)

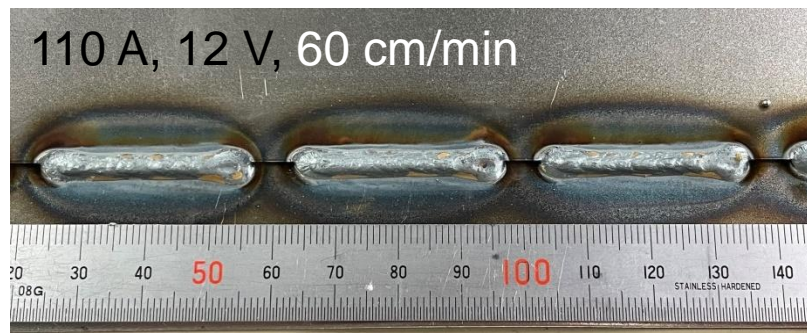
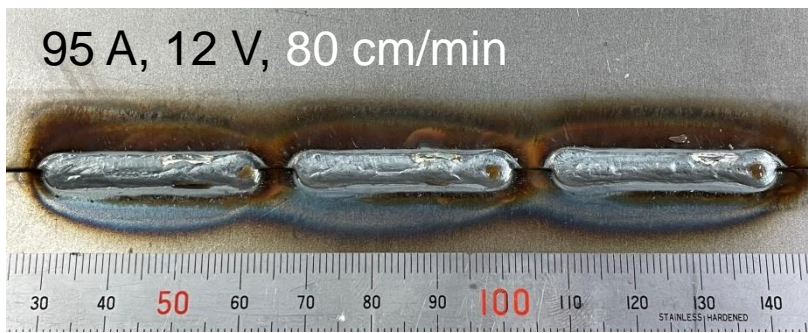
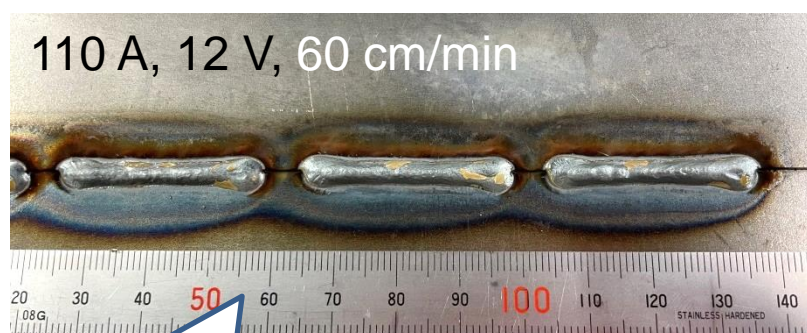
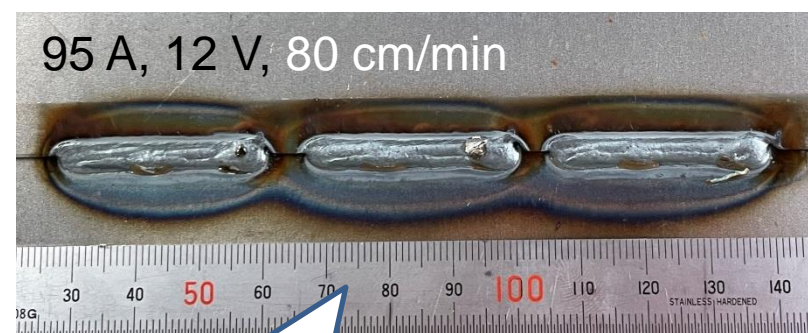
Plate thickness 0.6 mm, gap 0.3 mm tolerance to deviation aim

Current 70 A, voltage 14 V, welding speed: 70 cm/min, MAG gas, wire diameter 1.0 mmφ



Welding Sample (Mild Steel, CO2 Welding)

Lap joint welding of 0.8 mm thick plate (wire diameter $\phi 1.2$)


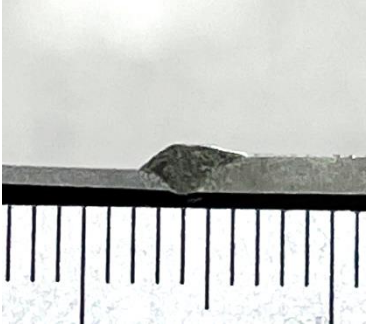


Gap	Conventional Synchro-feed	Push-arc process
0 mm	<p>110 A, 12 V, 60 cm/min</p> 	<p>95 A, 12 V, 80 cm/min</p> 
0.8 mm	<p>110 A, 12 V, 60 cm/min</p> 	<p>95 A, 12 V, 80 cm/min</p> 

Difficult to increase welding speed

Wide beads have been achieved

Welding Sample (Mild Steel, CO2 Welding)

Lap joint welding of 0.8 mm thick plate (wire diameter $\phi 1.2$)

Gap	Conventional Synchro-feed	Push-arc process
0 mm	 <p>Emboss bead</p>	 <p>Flat and wide bead</p>
0.8 mm	 <p>Emboss bead</p>	 <p>Flat and wide bead</p>

Welding Sample (Galvanized Sheet Steel, MAG Welding)



Conventional Synchro-feed
85 A, 16 V, 80 cm/min.
Galvanized sheet steel, **thickness 1.0 mm**
Butt joint (wire diameter $\phi 1.0$)



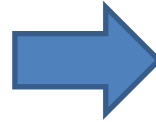
Push-arc process
85 A, 16 V, 80 cm/min.
Galvanized sheet steel, **thickness 1.0 mm**
Butt joint (wire diameter $\phi 1.0$)

Stable beads of uniform width are formed through the action of expanding the molten pool even in the low current range, zinc vapor discharge is accelerated, but no pit generation was observed.

Welding of Galvanized Sheet Steel by Push-Arc Process

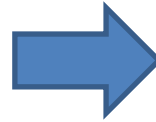
By using the push-arc process, pore defects such as blowhole are expected to be reduced.

① In the push-arc process, **excess weld metal** becomes lower in height.



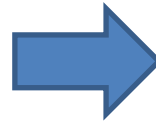
The time to release zinc gas mixed in is short.

② Use **arc force** to expand the molten metal so that the bead can be flattened.



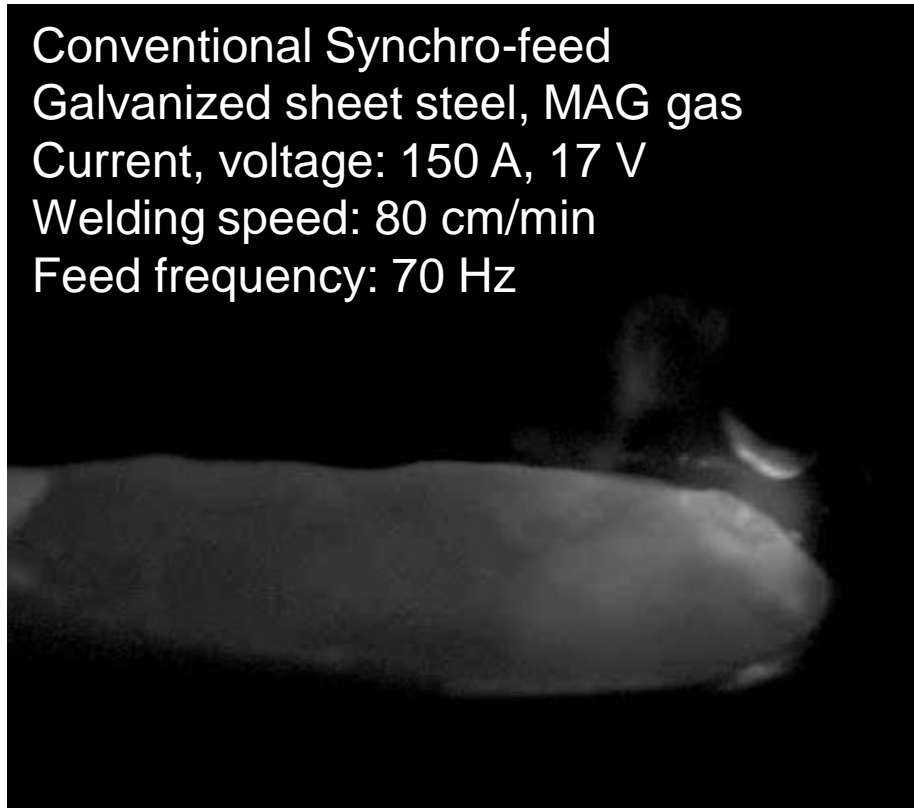
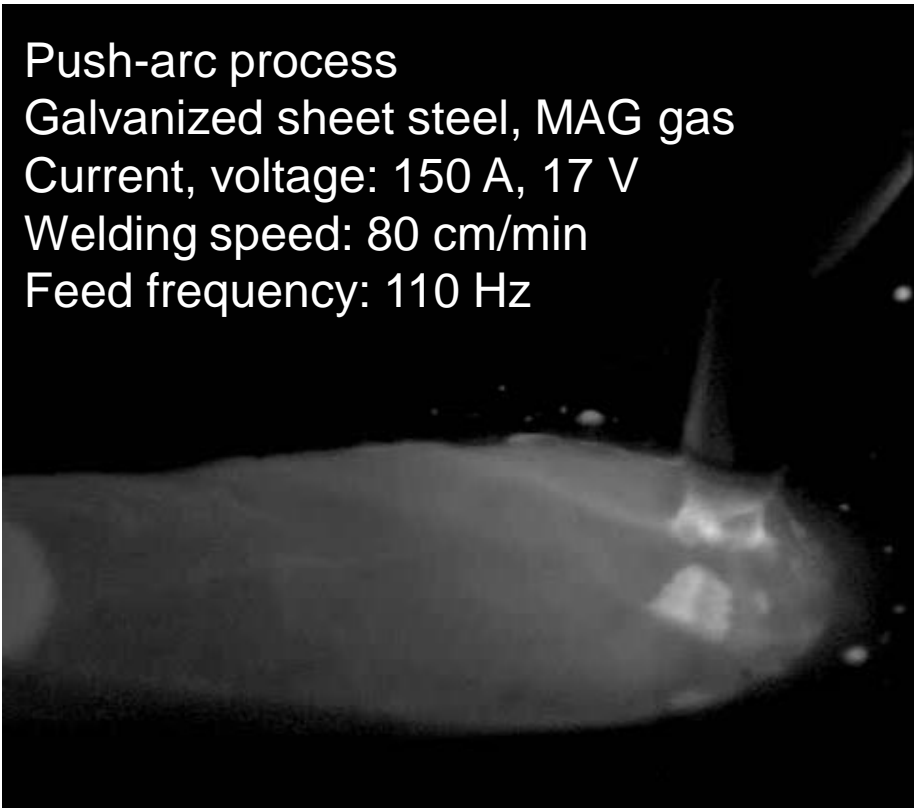
The molten metal shakes when it is expanded, which facilitates the release of gas mixed in.

③ For the push-arc process, **feed frequency** is high.

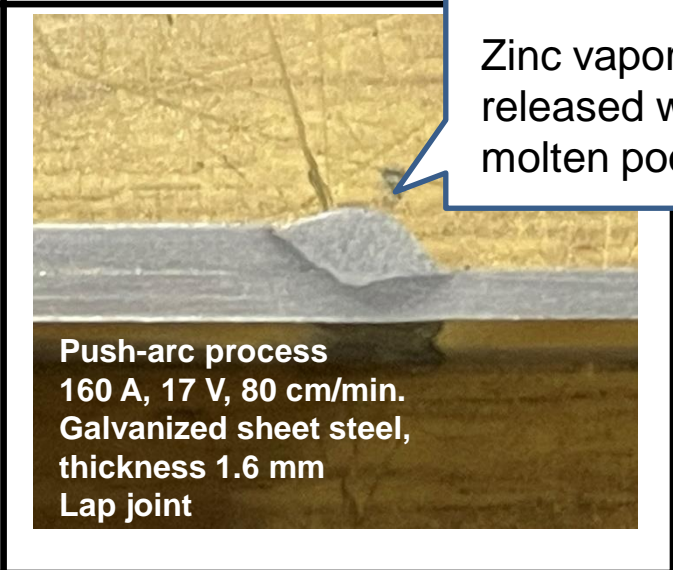
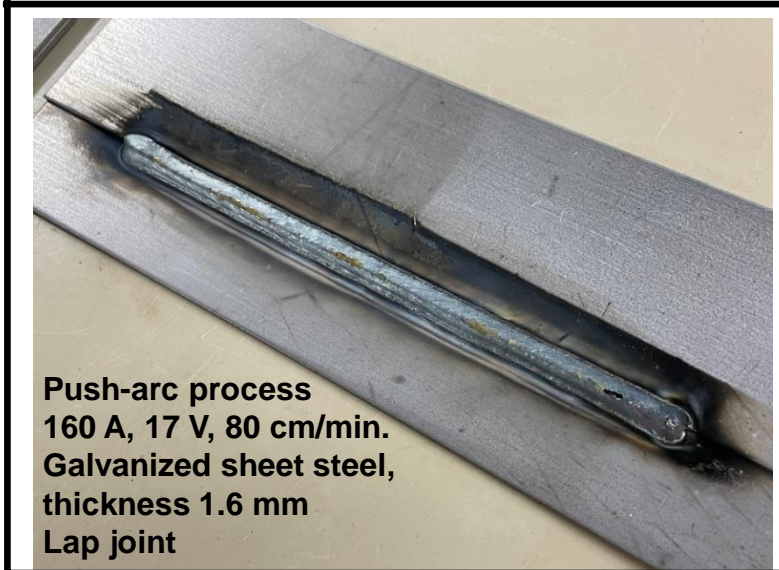
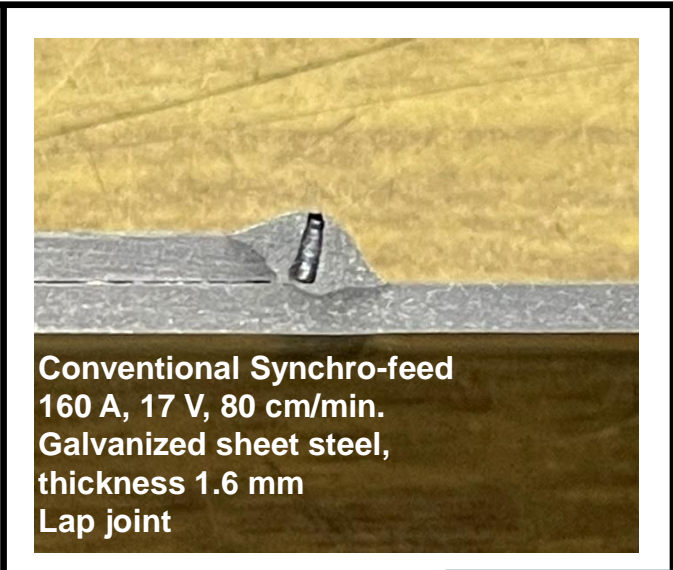
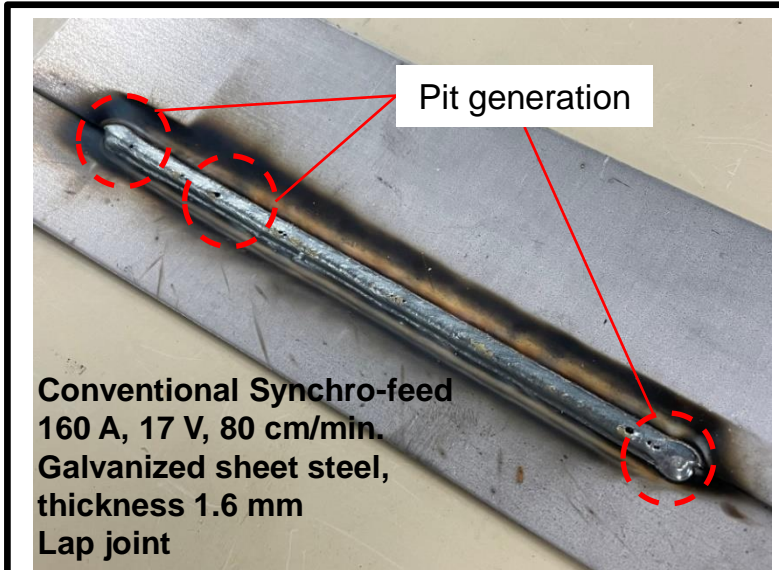


The increased number of times the molten metal is shaken makes it easy to release gas mixed in.

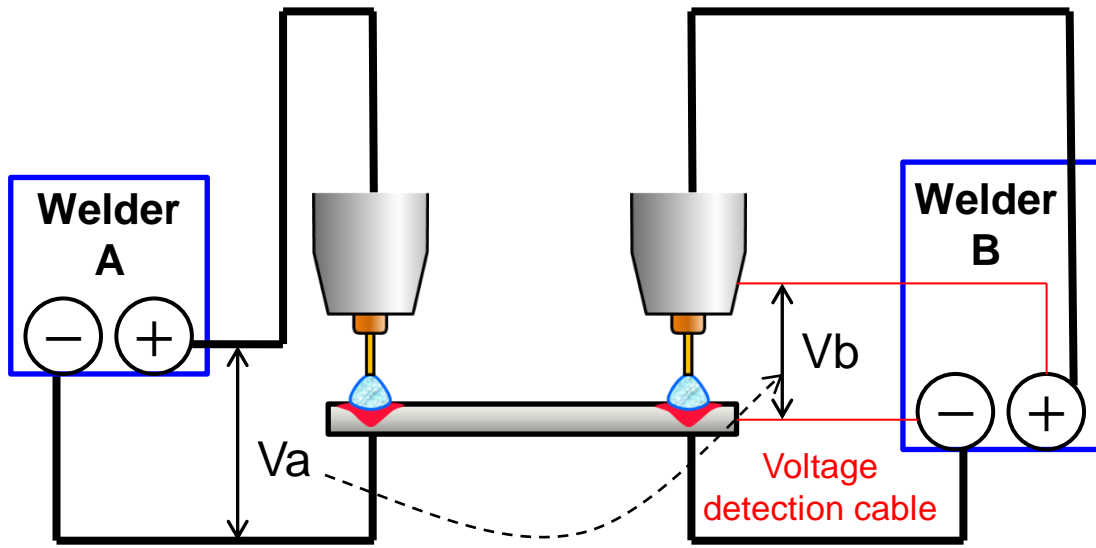
- Verify by comparison using high-speed video.



Welding Sample (Galvanized Sheet Steel, MAG Welding)



Causes of spatter generation when welding simultaneously using multiple welders



The voltage V_a affects the voltage V_b .

The voltage V_a generated by welder A affects the voltage FB of welder B.



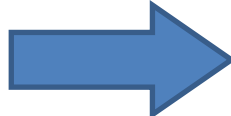
The voltage FB of welder B becomes $V_b + \alpha$. This causes **deviation of the timing of low spatter control** and an increase in spatter.

Learning Function for Spatter Reduction by Predicting Constriction

The new control is capable of reducing spatter even when welding simultaneously using multiple welders by predicting the timing of arc generation and not relying on the voltage FB.

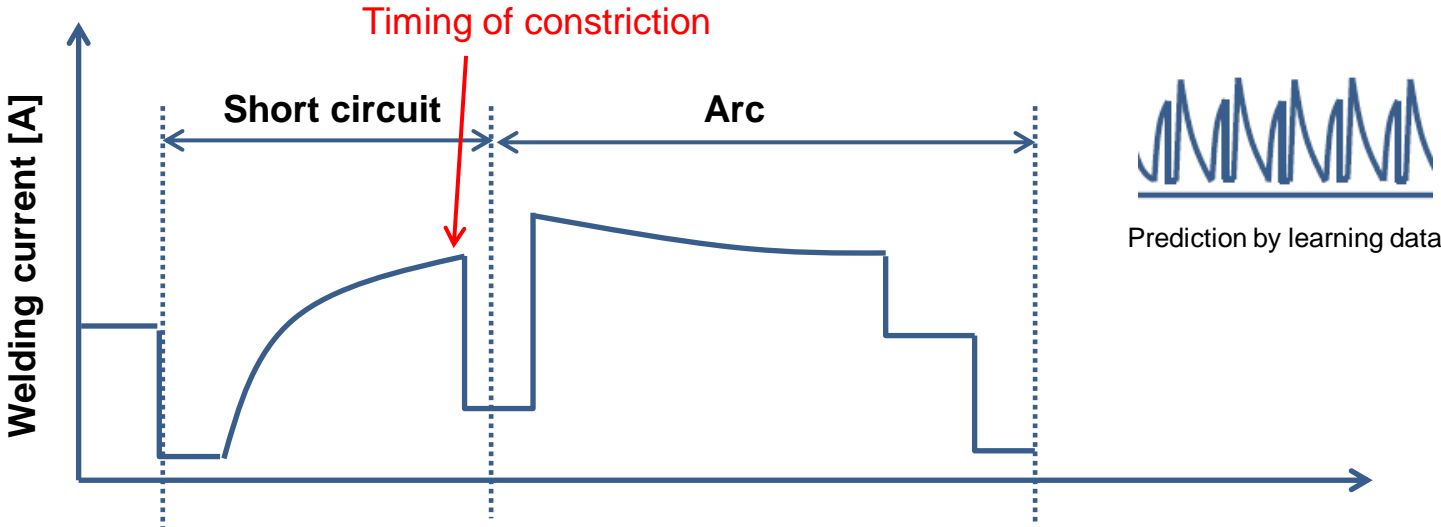
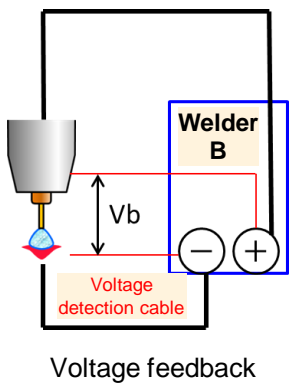
Conventional control

The voltage FB detects just before the arc is generated, and current is sharply reduced.



New control

The timing of generation of constriction is predicted based on the timing of arc reignition according to welding conditions and data learned from the past short-circuit cycle.



Learning Function for Spatter Reduction by Predicting Constriction

AS 溶接開始 1/4 UNIT1

溶接機 1:WID01 WBPL

条件ファイルID 0 リトライ番号 0 リスタート番号 0

溶接法 2:500A Co2 DC φ1.2 (SFFlat)

電流条件種別 送給速度 電流

スロープ条件種別 時間 距離

溶接制御種別 標準

ロボット動作番号 0

選択

↑

↓

書き込み

アーク電圧直接検出 無効 有効

? アーク電圧の直接検出を行うかどうかを設定します。

溶接定数 10/10 UNIT1

AS時のワイヤバッファ原位置復帰タイムアウト時間 2.0sec

AS時のワイヤバッファ原位置復帰異常時の動作 アラーム インフォメ

複数台同時溶接制御 無効 有効

サーボ送給接続先 溶接機 ファイ送給制御装置

ワイヤクランプ 無効 有効

A印時クランプ調整時間 0msec

インチング/リトラクト時アンクランプ調整時間 50msec

インチング/リトラクト時クランプ調整時間 50msec

フィードバックワイヤクランプ間調整時間 0msec

レーザーハイブリッド同期制御 無効 有効

溶接電圧一元調整 相対 比率

2次側パワーケーブル合計長さ 20m 30m

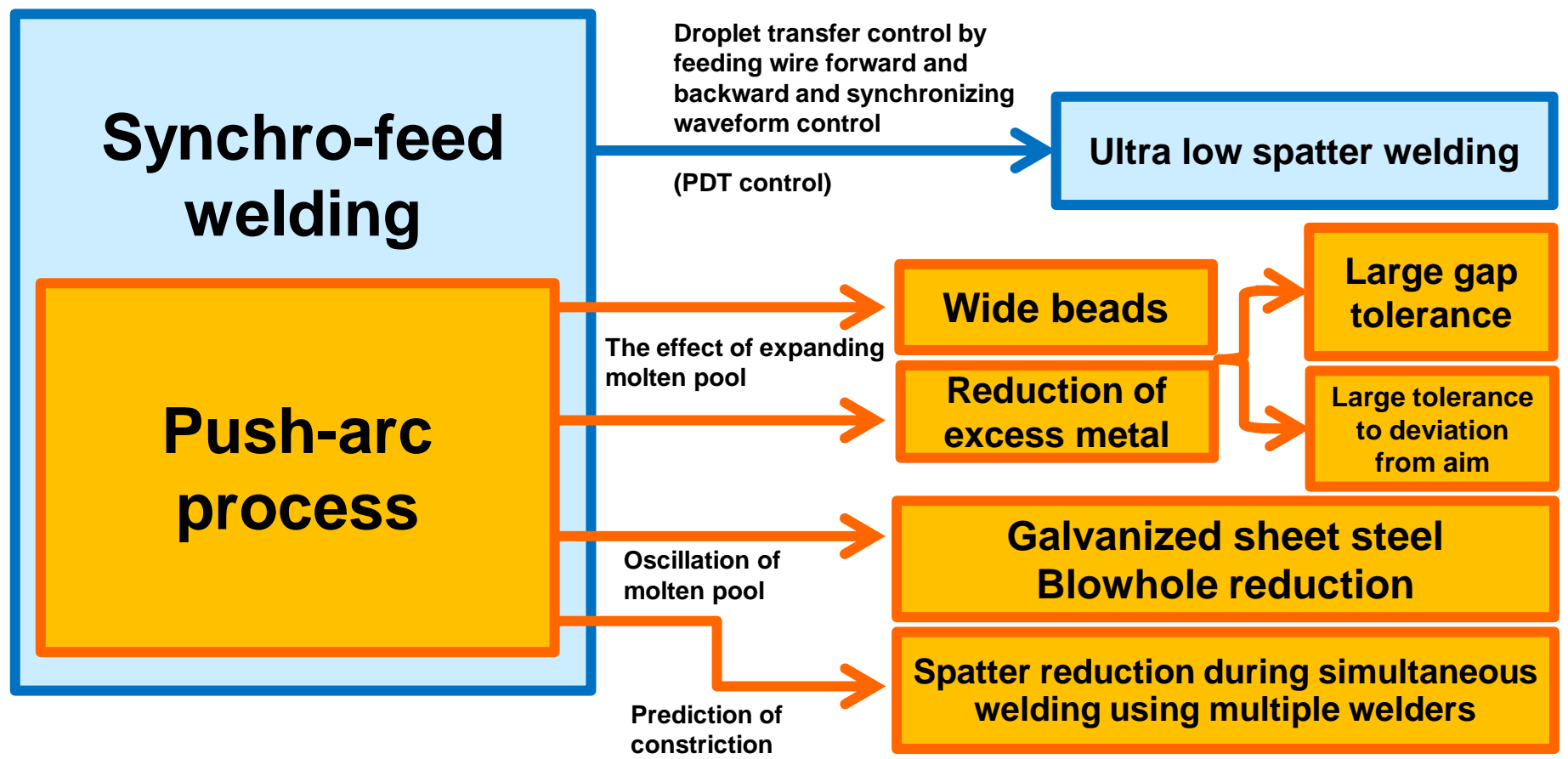
2次側パワーケーブル断面積 数値指定 80sq

? 溶接機の2次側パワーケーブルの断面積を入力してください。[22-200]

書き込み

1. The push-arc process allows low spatter welding similar to conventional Synchro-feed.
2. The push-arc process is capable of forming wide beads even on thin sheets, increasing joint tolerance.
3. In the welding of galvanized steel sheets, reduction of blowholes and pits can be expected.
4. In welding with multiple welders, the predictive learning function can prevent spatter from increasing.

Summary of Push-Arc Process



The push-arc process provides **high-quality welding using Synchro-feed** in an even wider range of applications

Welding process that alternates Synchro-feed welding and pulse welding

Video



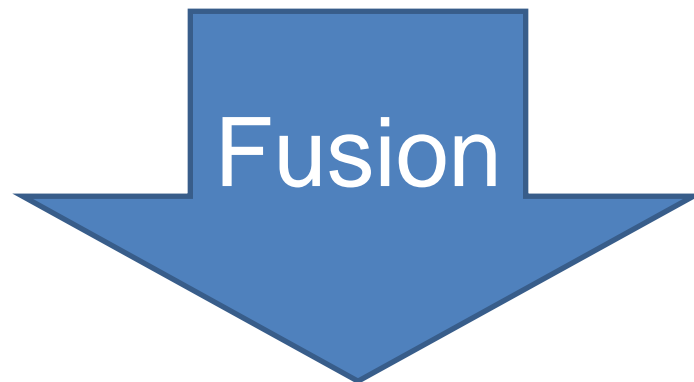
- **Expansion of the scope of application by heat input control**
Supports a wide range of plate thicknesses from 1 mm to 4 mm
- **Beautiful bead appearance**
Beautiful scale-like beads are possible
- **Easy-to-use welding instructions**
Average current and simple setting of pulse conditions only

Synchro-feed

- Maximum current 150 A
Forward and backward feeding of wire
- Thin plate welding
Due to low input heat, does not burn through, even on thin plates
- Emboss beads form easily

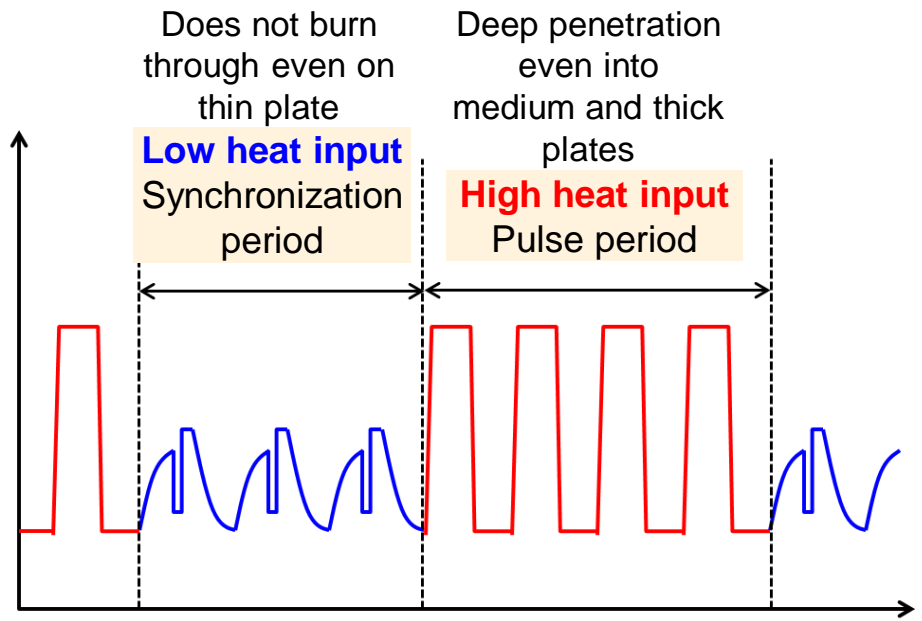
Pulse welding

- Maximum current 400 A
Forward feeding of wire
- Medium and thick welding
Deep penetration at high pulsed current
- A burn through occurs



Synchro-feed pulse welding

Video





Current waveform

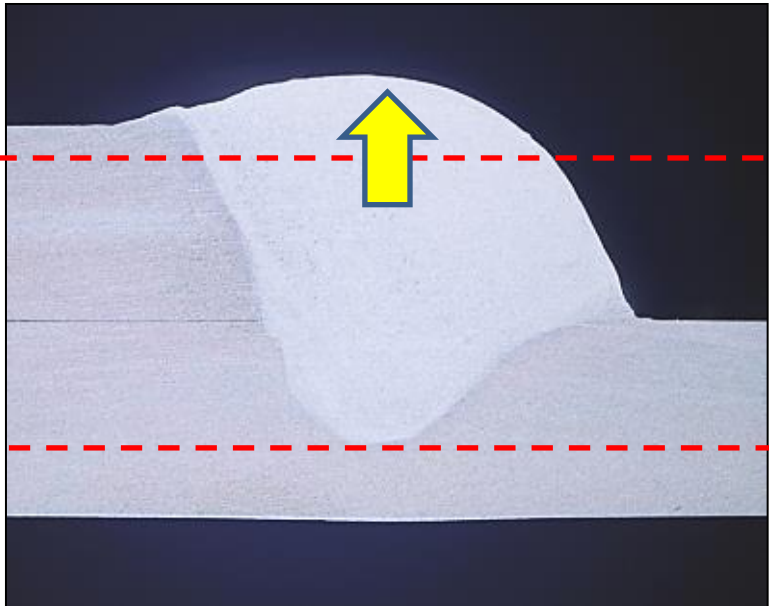


Welding process that repeats Synchro-feed and pulse at a determined frequency

Comparison of Welding Processes

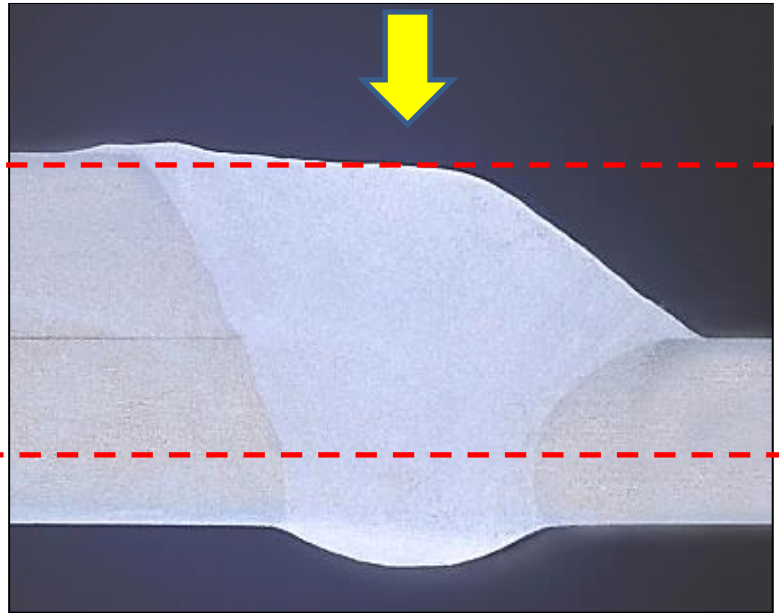
	Aluminum Synchro-feed Pulse welding process	Aluminum Synchro-feed Welding process
Appropriate weld plate thickness	2.0 mm - 4.0 mm	1.0 mm - 1.5 mm
High-speed welding	200 A: 100 cm/min	130 A: 80 cm/min
Weld bead appearance	<p>Sharp scale-like beads</p> 	<p>Smooth</p>  <p>* With weaving</p>
Disadvantages	Slightly more spatter is generated than Synchro-feed	Emboss beads form easily due to low heat input Example) Butt welding

① Pulse ratio allows adjustment of the height of excess metal and penetration



Pulse ratio 30%

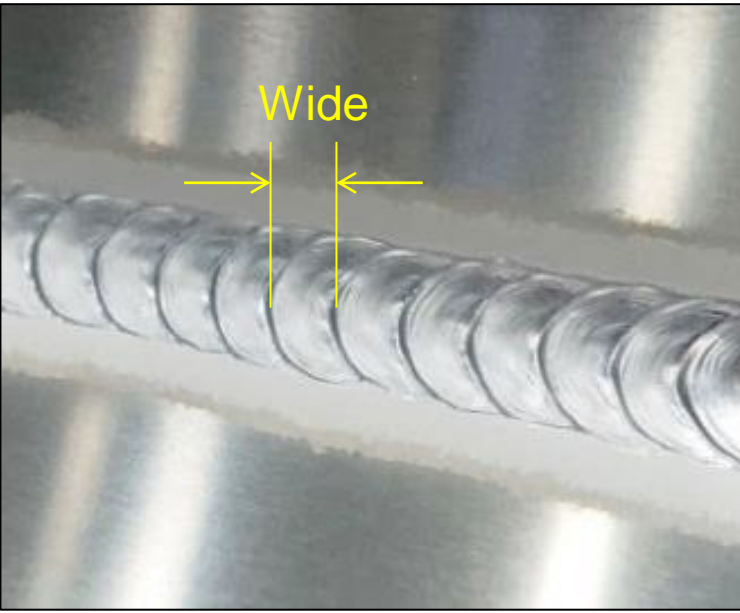
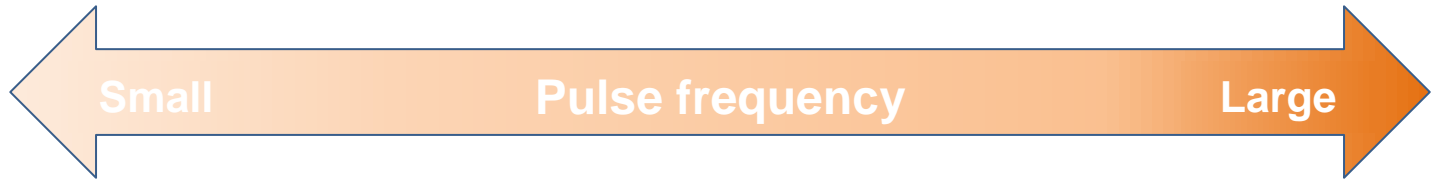
* Many Synchro-feed welding sections



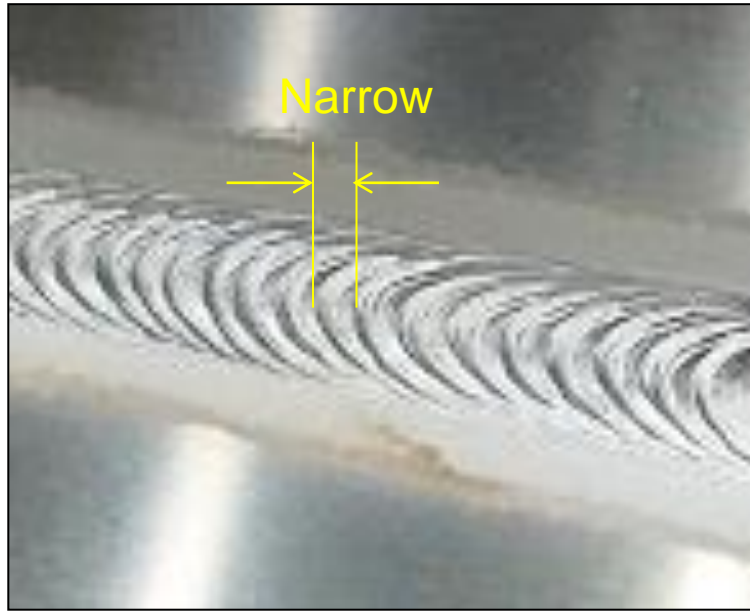
Pulse ratio 70%

* Many pulse welding sections

② Waves can be adjusted by pulse frequency.



Pulse frequency 1.5 Hz



Pulse frequency 4.0 Hz

② Summary of the relationship between pulse ratio and frequency

Bead width: thin
Penetration: shallow
←→
Bead width: wide
Penetration: deep

Waves Spacing: wide

 Waves Spacing: narrow

		パルス比率					
		20%		50%		80%	
周波数	2Hz						
	4Hz						
	8Hz						

* Set current/voltage and welding speed are fixed.
 Welding conditions
 Synchro side setting: 100 A/12.0 V, pulse side setting: 150 A/18.0 V, base metal: A5052 (3 mmt)
 Wire: A5356 (1.2 mmφ), Shield gas: 100% Ar, Welding speed: 45 cm/min, Joint: lap

- ③ AS commands allows easy settings of current, voltage, pulse ratio, etc.

Average current by setting

The screenshot displays the 'AS 溶接開始' (AS Welding Start) screen. At the top, it shows '2/7' and 'UNIT1'. The settings are as follows:

- 溶接機 (Welder): 1:WID01 WBPL
- 条件設定 (Condition Setting): 簡易 (Simple) 詳細 (Detailed)
- 溶接電流 (Welding Current): 150 A
- アーク長微調整 (Arc Length Fine Adjustment): 0
- (シンクロ)溶接電流 (Synchro) Welding Current: 150 A
- (シンクロ)アーク長微調整 (Synchro) Arc Length Fine Adjustment: 0
- (パルス)溶接電流 (Pulse) Welding Current: 150 A
- (パルス)アーク長微調整 (Pulse) Arc Length Fine Adjustment: 0
- 周波数 (Frequency): 1.0 Hz
- パルス比率 (Pulse Ratio): 50%
- 溶接速度 (Welding Speed): 80 cm/m

Annotations on the screenshot:

- A blue dashed box highlights the '溶接電流' and 'アーク長微調整' fields, with an arrow pointing to the text 'Average current by setting'.
- A red dashed box highlights the '(シンクロ)溶接電流', '(シンクロ)アーク長微調整', '(パルス)溶接電流', and '(パルス)アーク長微調整' fields, with an arrow pointing to the text 'Synchro and pulse current settings'.
- A green dashed box highlights the '周波数' and 'パルス比率' fields, with an arrow pointing to the text 'Setting frequencies and ratios'.

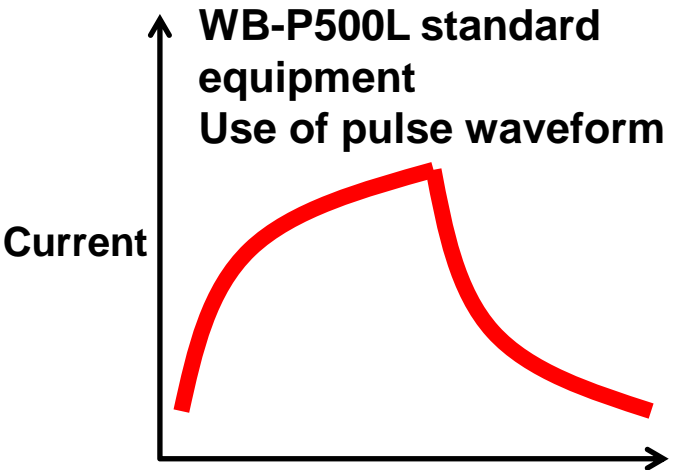
The waveform diagram at the bottom shows the welding current over time. It includes labels for 'スタートパルス時間' (Start Pulse Time), '1 周期' (1 Cycle), 'a', and 'b'. The pulse ratio formula is given as:

$$\text{パルス比率} = \frac{b}{a+b} \times 100$$

Legend for the waveform:

- a. シンクロフィード[®] 溶接 (Synchro Feed[®] Welding)
- b. パルス溶接 (Pulse Welding)

A note at the bottom left states: '詳細設定を行う場合には、溶接条件ファイルで指示を行ってください。' (When performing detailed settings, please follow the instructions in the welding condition file.)



Bead appearance	Bead cross-section	Welding conditions
		Base metal (thickness): A5052 (3.0 mmt) Wire (diameter): A5356 (1.2 mmφ) Joint: lap Set current/voltage: (SF) 80 A/12.0 V, (PLS) 200 A/20.0 V Pulse ratio: 70% Synchro pulse frequency: 4.0 Hz Welding speed: 55 cm/min Position: horizontal
		Base metal (thickness): A6063 (2.0 mmt) Wire (diameter): A4043 (1.2 mmφ) Joint: pipe (T corner) Set current/voltage: (SF) 70 A/13.0 V, (PLS) 130 A/18.0 V Pulse ratio: 40% Synchro pulse frequency: 1.5 Hz Welding speed: 40 cm/min Position: horizontal
		Base metal (thickness): A5052 (2.0 mmt) Wire (diameter): A5356 (1.2 mmφ) Joint: lap Gap: 2 mm Set current/voltage: (SF) 80 A/12.0 V, (PLS) 140 A/18.0 V Pulse ratio: 35% Synchro pulse frequency: 8.0 Hz Welding speed: 70 cm/min, Position: horizontal

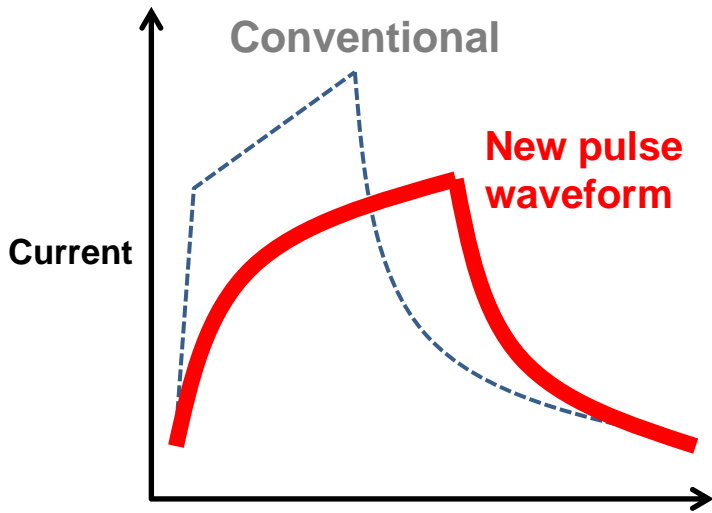
Soft Aluminium Application to pipe saddle type

[Video](#)



Features

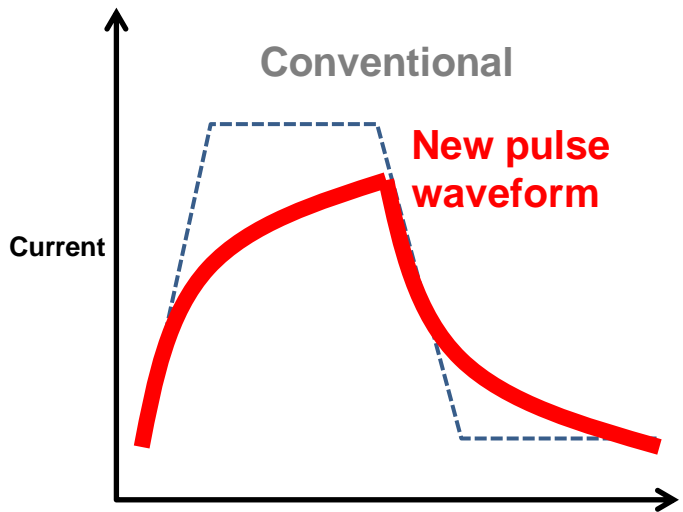
- New pulse waveform which excels at thin plate welding has been adopted
- Undercut is decreased by new pulse waveform
- Wide weld bead



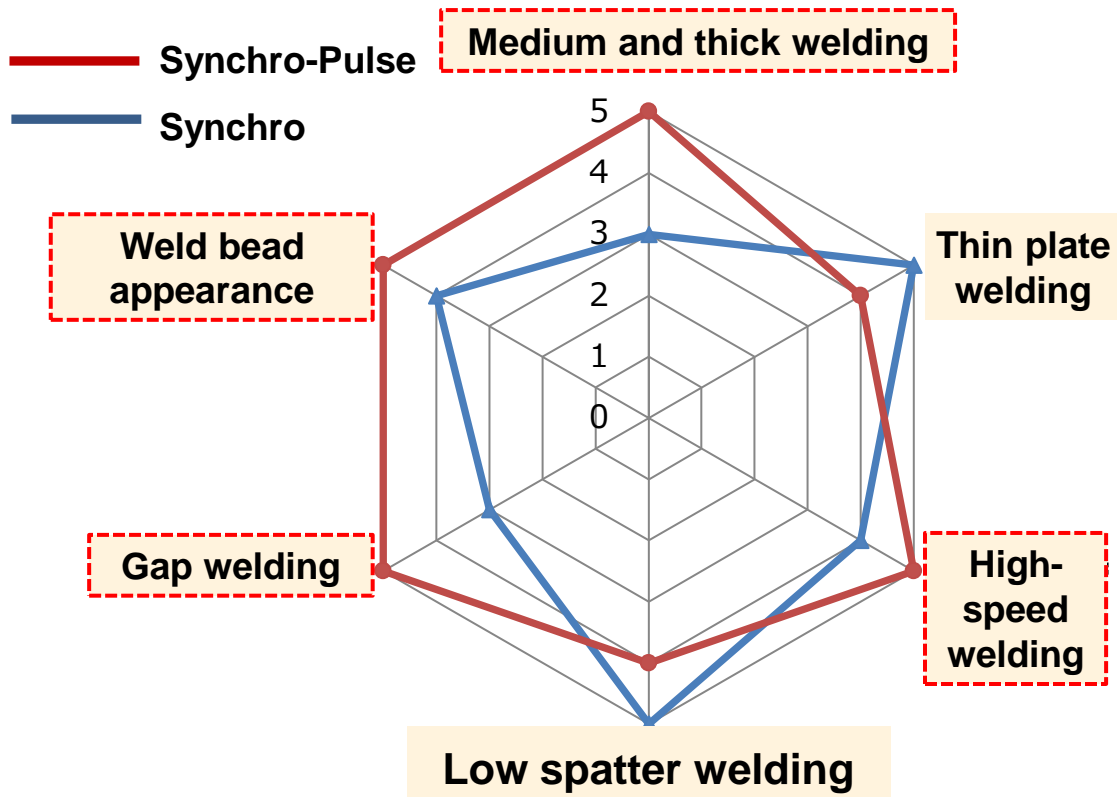
Bead appearance	Bead cross-section	Welding conditions
		Workpiece (thickness): SUS304 (2.0 mmt) Wire (diameter): SUS308 (1.2 mmφ) Joint: T corner Set current/voltage: (SF) 120 A/13.0 V, (PLS) 180 A/19.0 V Pulse ratio: 40% Synchro pulse frequency: 10 Hz Welding speed: 70 cm/min Position: horizontal, Push angle: 5°, Torch angle: 40°
		Base metal (thickness): SUS304 (1.0 mmt) Wire (diameter): SUS308 (1.2 mmφ) Joint: lap Set current/voltage: (SF) 120 A/12.0 V, (PLS) 180 A/18.0 V Pulse ratio: 40% Synchro pulse frequency: 10 Hz Welding speed: 120 cm/min Position: downward 40°, Push angle: 5°, Torch angle: 10°
		Workpiece (thickness): SUS430 (0.8 mmt) Wire (diameter): SUS430 (1.0 mmφ) Joint: lap Set current/voltage: (SF) 140 A/11.0 V, (PLS) 190 A/21.0 V Pulse ratio: 50% Synchro pulse frequency: 15 Hz Welding speed: 180 cm/min Position: downward 40°, Push angle: 5°, Torch angle: 5°

Features

- Pulse waveform which excels at thin plate welding has been adopted
- Wide weld bead
- Penetration into base metal is reduced



Bead appearance	Bead cross-section	Welding conditions
		Base metal (thickness): Spcc (2.0 mmt) Wire (diameter): CuSi (1.2 mmφ) Joint: T corner Set current/voltage: (SF) 100 A/13.5 V, (PLS) 130 A/18.5 V Pulse ratio: 50% Synchro pulse frequency: 10 Hz Welding speed: 110 cm/min Position: horizontal, Push angle: 10°, Torch angle: 40°
		Base metal (thickness): Spcc (1.0 mmt) Wire (diameter): CuSi (1.0 mmφ) Joint: double flare Set current/voltage: (SF) 100 A/13.0 V, (PLS) 140 A/21.5 V Pulse ratio: 50% Synchro pulse frequency: 12 Hz Welding speed: 150 cm/min Position: horizontal



[Main features of Synchro-Pulse]

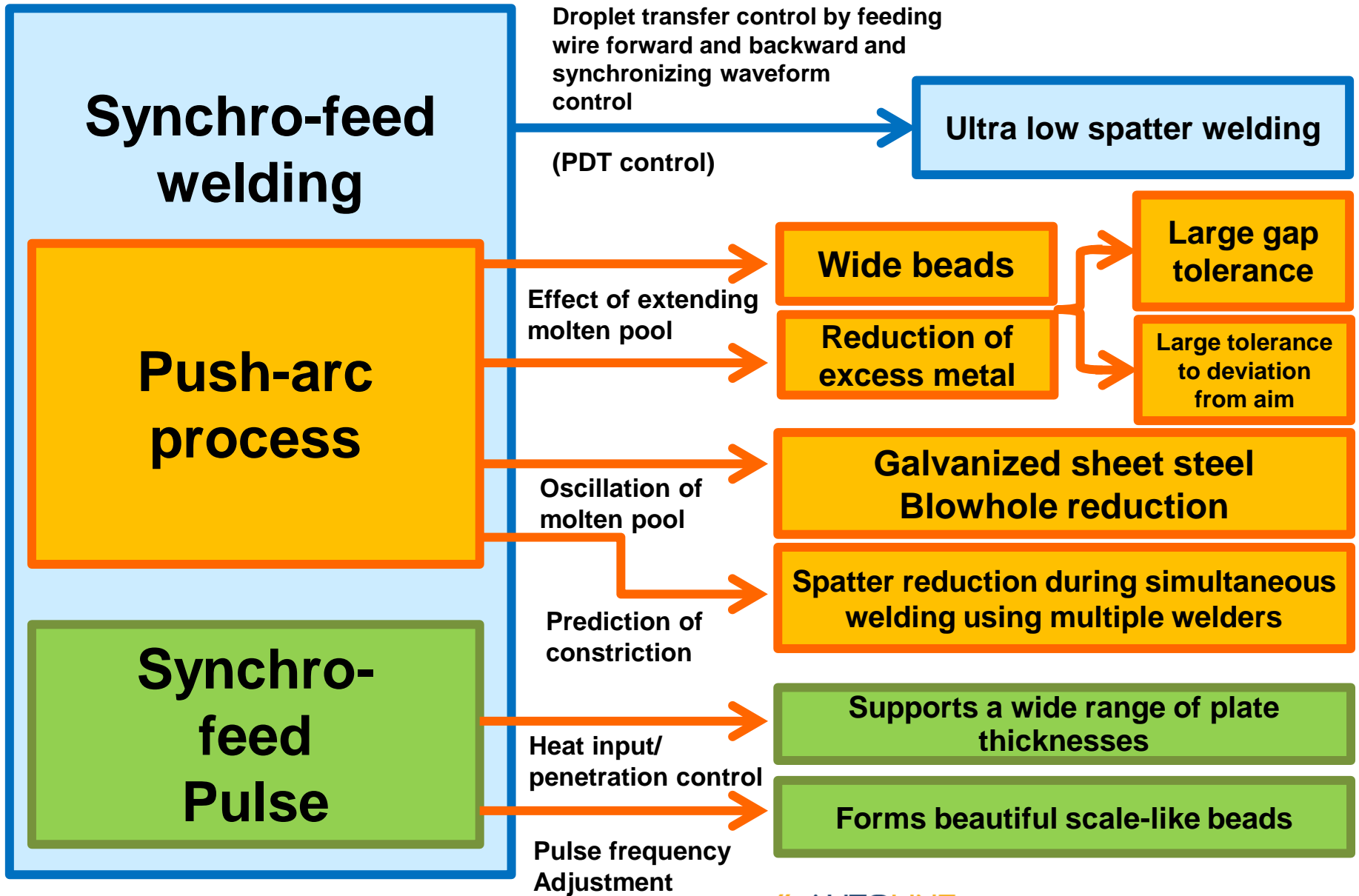
■ Extended heat input control range

- Capable of welding medium and thick plates that were difficult to weld with Synchro-feed (3 - 4mm)
- Easy to set welding conditions even for thin plate gap welding
- High-speed welding allows formation of a wide range of weld beads

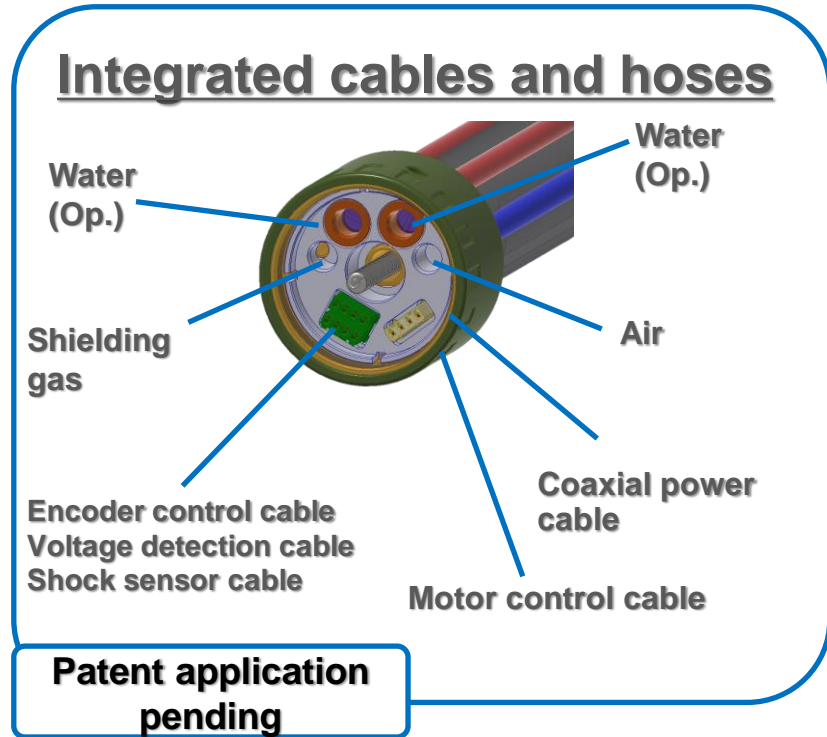
■ Formation of scale-like beads

- Capable of forming beautiful and sharp scale-like beads

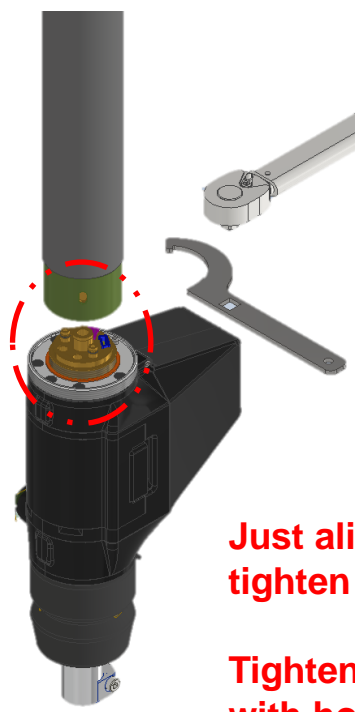
Summary of Features of Welding Control



Composite control cables reduce connection work hours by 95%.



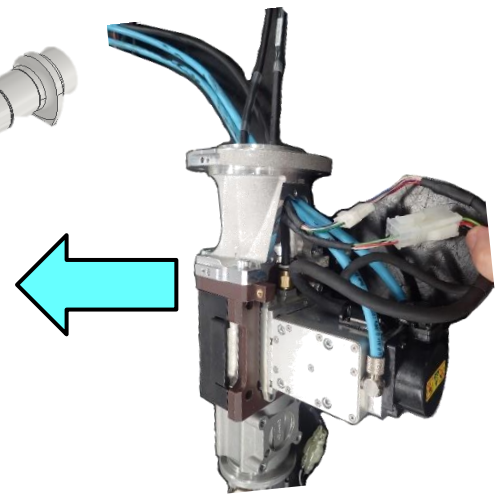
New product



Just align the connector parts and tighten the nuts.

Tightening torque can be controlled with hook wrench (for 9.6 square hole)

Conventional



- Cables and hoses between pull F and coaxial PC are collected in one place
- Connection can be made in one action and work is completed in about 2 minutes. (Previously, it took more than 30 minutes)
- Even an inexperienced user can install it easily and securely.

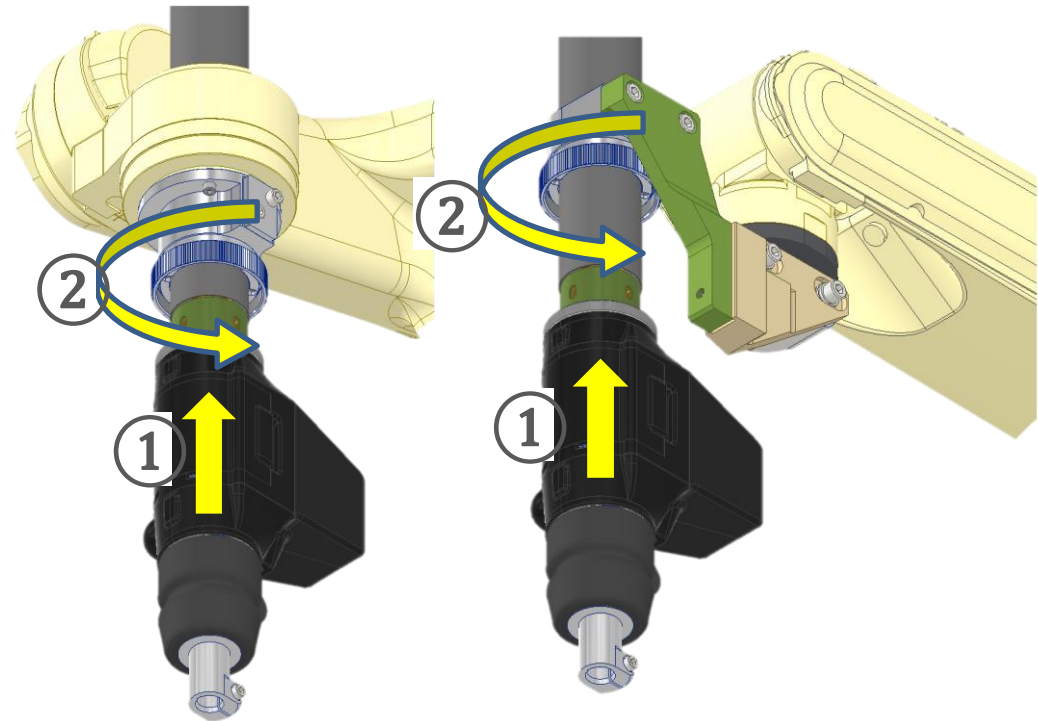
Simple and Easy Connection

▪ Can be easily installed in the bracket in two actions.

① Insert pull F, coaxial PC into bracket

② Tighten and secure the nut.

Connection work hours:
about 1 minute



NB6 type

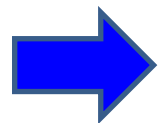
NV8 type



Easy Maintenance

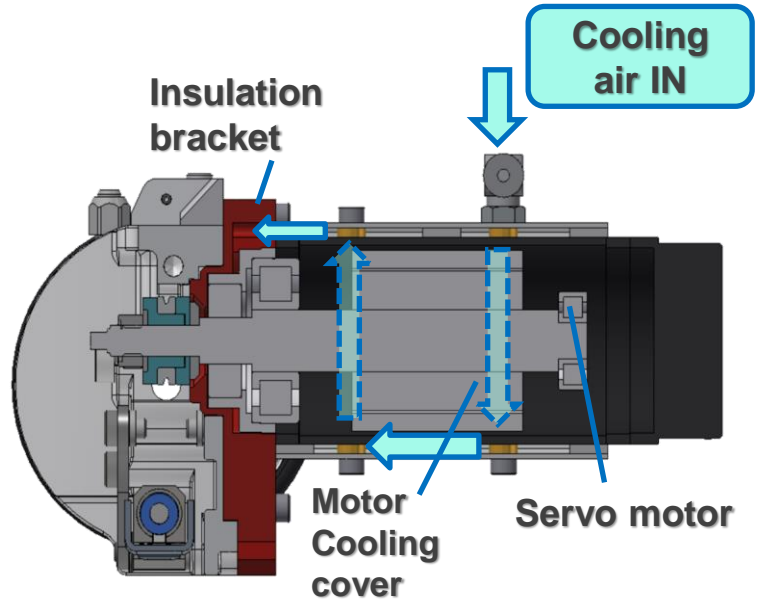
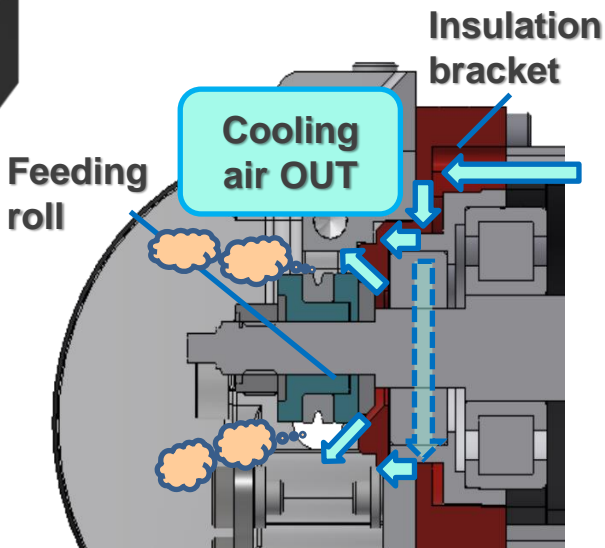
Auto-cleaning function reduces cleaning frequency of wire feeder by 90%.

Equipped with air purge function that automatically discharges wire shavings



Cleaning frequency reduced to 1/12!
(Once/week → Once/3 months)

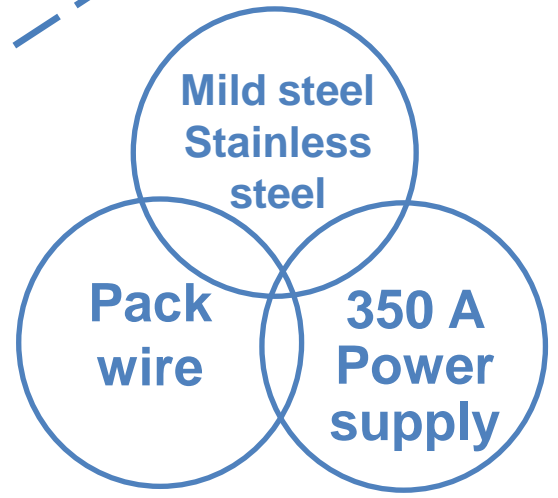
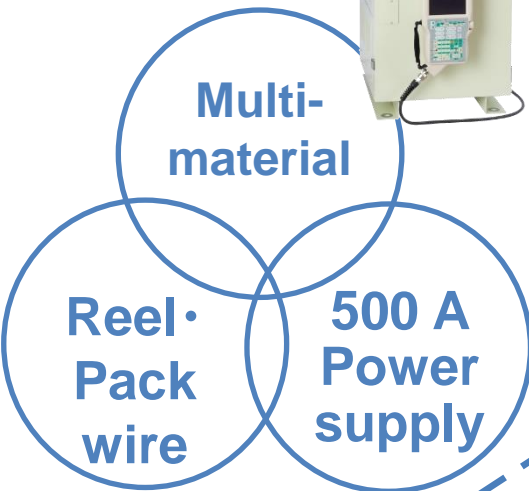
- Reduces time and effort required for cleaning and problems caused by forgetting to clean, and provides **productivity improvement** to customers.





Two Types of Synchro-Feed to Choose From

Synchro-feed



Synchro-feed Lite

Items	Synchro-feed Evolution	Synchro-feed Evolution Lite
Main components	Wire buffer Pull feeder Push feeder	Pull feeder
Applicable materials	Mild steel, stainless steel, Aluminum	Mild steel, stainless steel
Wire stock method	Pack/reel	Pack wire
Supported welders	WB-P500L	WB-P350L
Maximum welding current	CO2: 400 A MAG: 350 A	CO2: 280 A MAG: 350 A

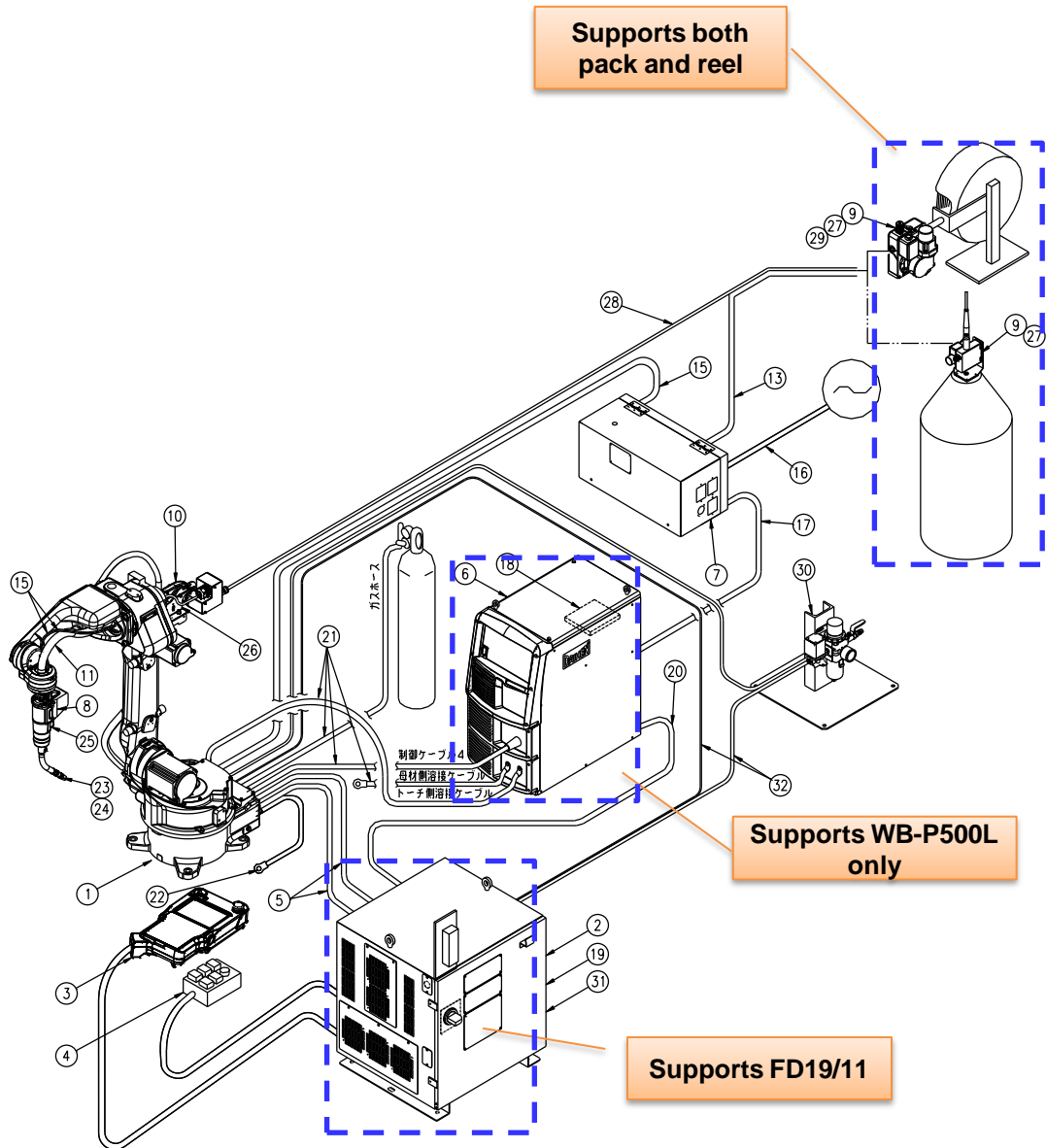
Synchro-Feed Configuration Comparison Table

		Synchro-feed Evolution	Synchro-feed I	Synchro-feed Evolution Lite	Synchro-feed I Lite
1	Manipulator	NB6/NB6L/NV8/NV8L/NV25			
2	Robot controller	FD19	FD19 / FD11	FD19	FD19
3	Welding power supply	WB-P350L/WB-P500L	WB-P500L	WB-P350L / WB-P500L	WB-P350L
4	Wire feed control unit	AFCA-S2W04			
5	Pull feeder	AFPS-2511	AFPS-2503	AFPS-2511	AFPS-2503
6	Coaxial power cable	L-12055 (for B6) L-12056 (for B6L) L-12057 (for NV8 and NV25) L-12058 (for NV8L)	L-11733 (for B6) L-11622 (for V8/V25) L-11880 (for B6L) L-11634 (for V8L)	L-12055 (for B6) L-12056 (for B6L) L-12057 (for NV8 and NV25) L-12058 (for NV8L)	L-11733 (for B6) L-11622 (for V8/V25) L-11880 (for B6L) L-11634 (for V8L)
7	Wire buffer	L-11610		Unnecessary (L-11610) Changed to mounting bracket	
8	Push feeder	AFS-2301		Unnecessary (AFS-2301)	
9	Conduit	L10597□			
10	High duty cycle kit	L11741H			

* To distinguish it from Synchro-feed Evolution, the current Synchro-feed is referred to as Synchro-feed I in this document.

* Support for FD11 other than Synchro-feed I is being planned

Synchro-Feed I System Configuration



Supports both pack and reel

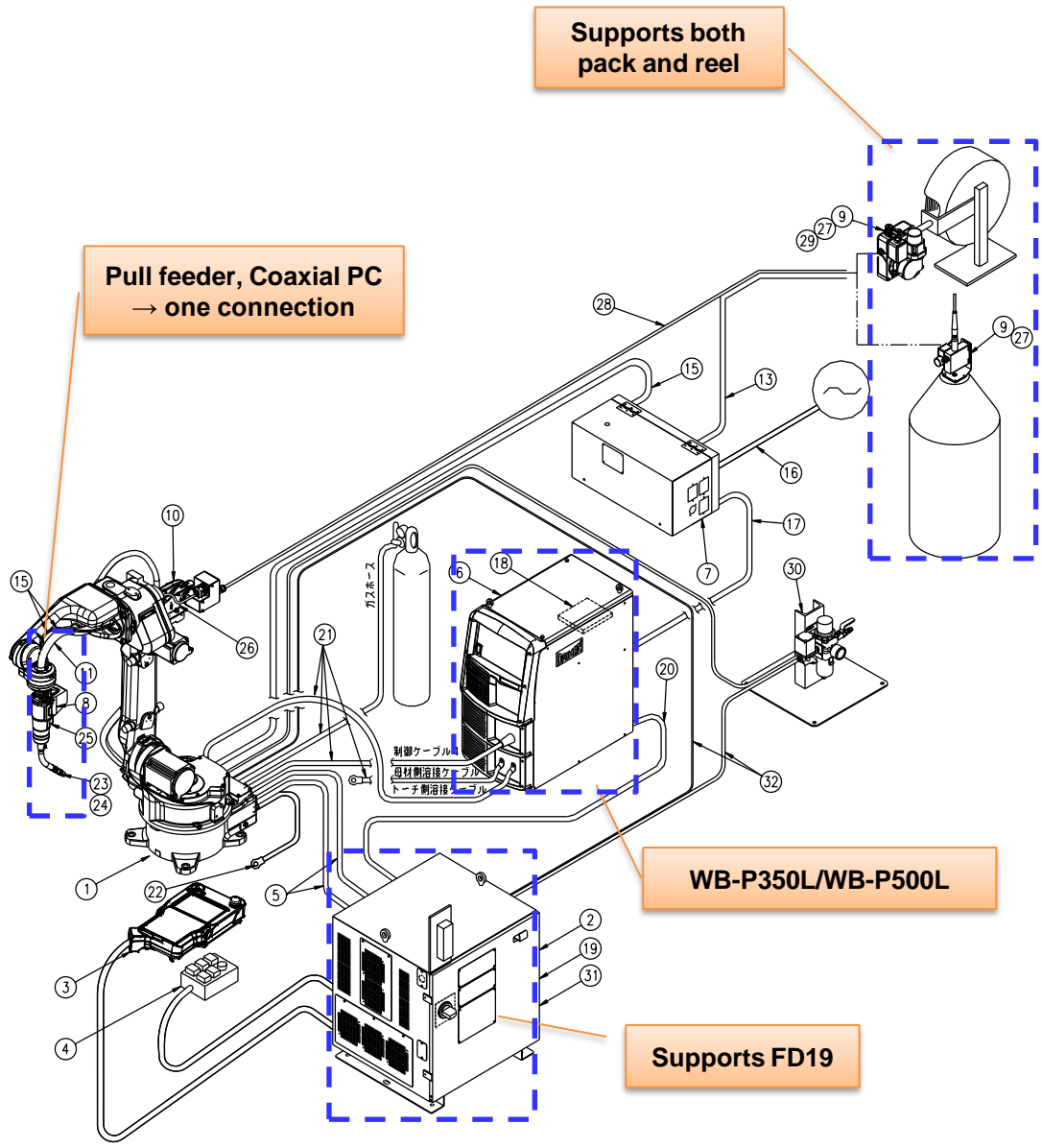
Supports WB-P500L only

Supports FD19/11

1	Manipulator	NB6/NB6L/NV8/NV8L/NV25
2	Robot controller	FD19 / FD11
3	Welding power supply	WB-P500L
4	Wire feed control unit	AFCA-S2W04
5	Pull feeder	AFPS-2503
6	Coaxial power cable	L-11733 (for B6) L-11622 (for V8/V25) L-11880 (for B6L) L-11634 (for V8L)
7	Wire buffer	L-11610
8	Push feeder	AFS-2301
9	Conduit	L10597□
10	High duty cycle kit	L11741H



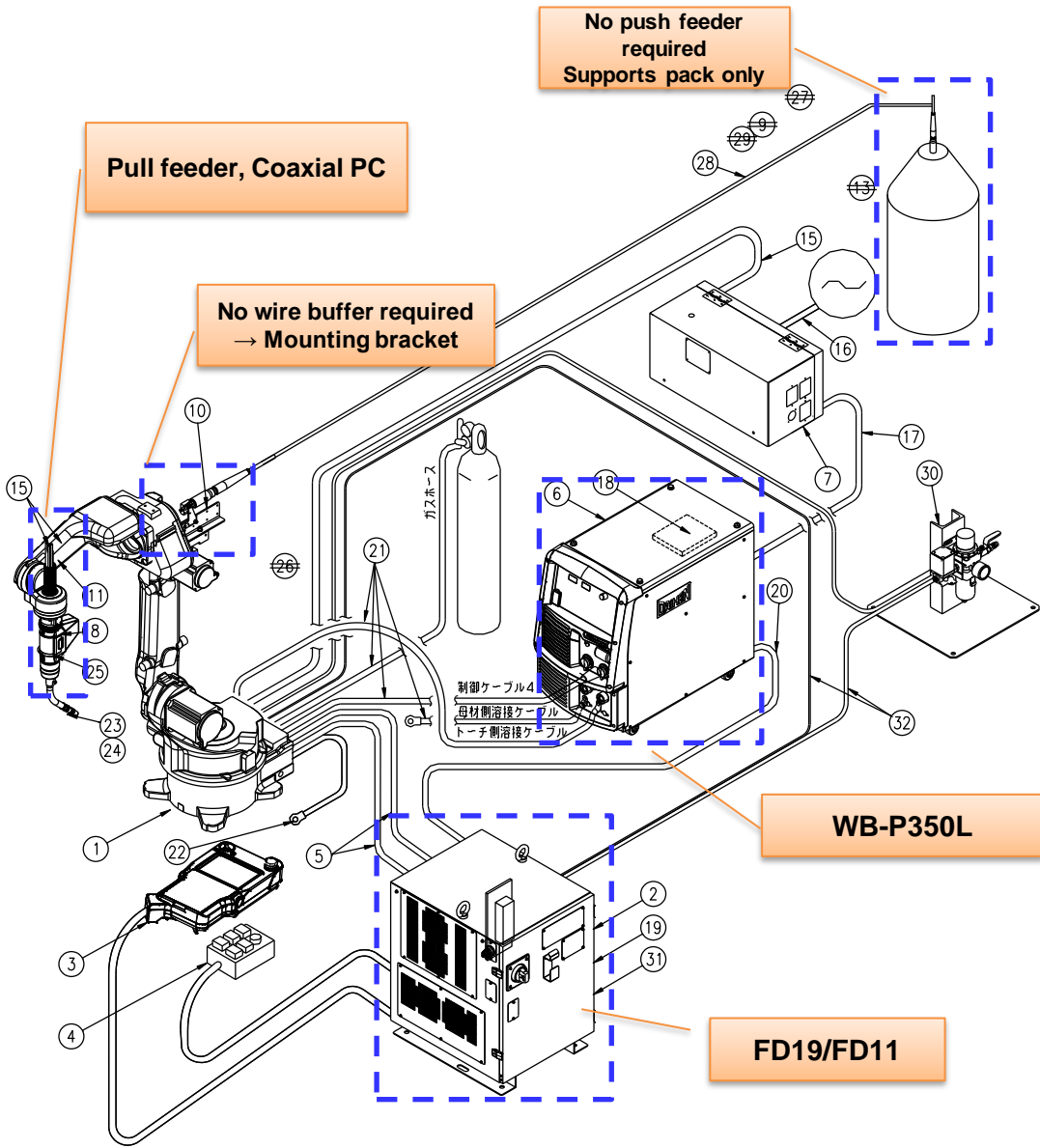
Synchro-Feed Evolution System Configuration



1	Manipulator	NB6/NB6L/NV8/NV8L/NV25
2	Robot controller	FD19
3	Welding power supply	WB-P350L/WB-P500L
4	Wire feed control unit	AFCA-S2W04
5	Pull feeder	AFPS-2511
6	Coaxial power cable	L-12055 (for B6) L-12056 (for B6L) L-12057 (for NV8 and NV25) L-12058 (for NV8L)
7	Wire buffer	L-11610
8	Push feeder	AFS-2301
9	Conduit	L10597□
10	High duty cycle kit	L11741H



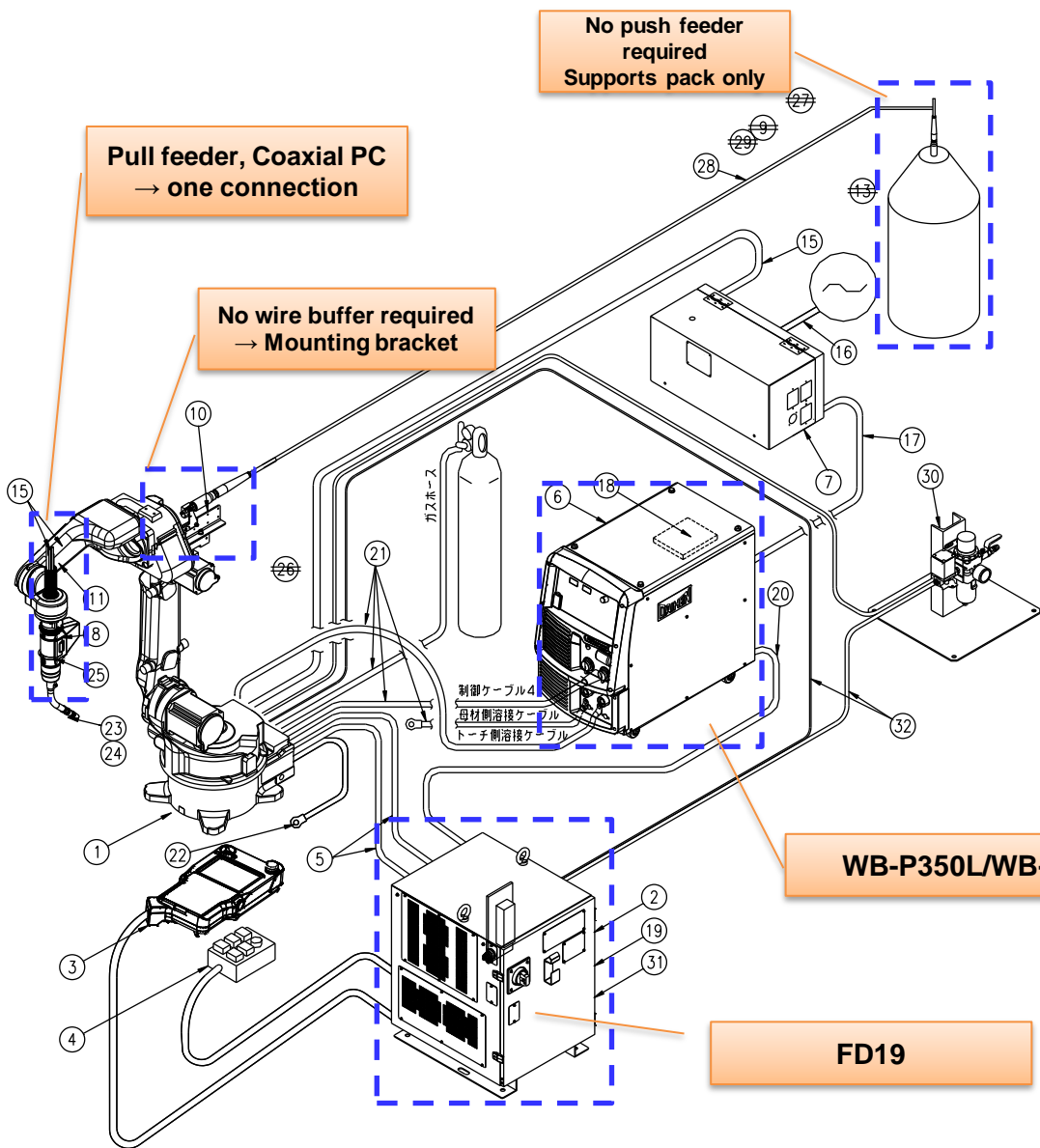
Synchro-Feed I Lite System Configuration



1	Manipulator	NB6/NB6L/NV8/NV8L/NV25
2	Robot controller	FD19
3	Welding power supply	WB-P350L
4	Wire feed control unit	AFCA-S2W04
5	Pull feeder	AFPS-2503
6	Coaxial power cable	L-11733 (for B6) L-11622 (for V8/V25) L-11880 (for B6L) L-11634 (for V8L)
7	Wire buffer	Unnecessary (L-11610) Changed to mounting bracket
8	Push feeder	Unnecessary (AFS-2301)
9	Conduit	L10597□
10	High duty cycle kit	L11741H



Synchro-Feed Evolution Lite System Configuration



1	Manipulator	NB6/NB6L/NV8/NV8L/NV25
2	Robot controller	FD19
3	Welding power supply	WB-P350L / WB-P500L
4	Wire feed control unit	AFCA-S2W04
5	Pull feeder	AFPS-2511
6	Coaxial power cable	L-12055 (for B6) L-12056 (for B6L) L-12057 (for NV8 and NV25) L-12058 (for NV8L)
7	Wire buffer	Unnecessary (L-11610) Changed to mounting bracket
8	Push feeder	Unnecessary
9	Conduit	L10597□
10	High duty cycle kit	L11741H

WB-P350L/WB-P500L

FD19